Jordan Normal Form

§1. Jordan's Theorem

Definition The *n* by *n* matrix $J_{\lambda,n}$ with λ 's on the diagonal, 1's on the superdiagonal and 0's elsewhere is called a *Jordan block* matrix. A *Jordan* matrix or matrix in *Jordan normal form* is a block matrix that is has Jordan blocks down its block diagonal and is zero elsewhere.

Theorem Every matrix over **C** is similar to a matrix in Jordan normal form, that is, for every A there is a P with $J = P^{-1}AP$ in Jordan normal form.

§2. Motivation for proof of Jordan's Theorem

Consider Jordan block $A = J_{\lambda,n}$, for example,

$$A = J_{5,3} = \begin{pmatrix} 5 & 1 & 0\\ 0 & 5 & 1\\ 0 & 0 & 5 \end{pmatrix}.$$

We see that

$$egin{aligned} A {f e}_1 &= 5 {f e}_1 \ A {f e}_2 &= {f e}_1 + 5 {f e}_2 \,. \ A {f e}_3 &= {f e}_2 + 5 {f e}_3 \end{aligned}$$

Writing $A_5 = A - 5I$ this becomes:

$$A_5 \mathbf{e}_1 = \mathbf{0}$$
$$A_5 \mathbf{e}_2 = \mathbf{e}_1$$
$$A_5 \mathbf{e}_3 = \mathbf{e}_2$$

which can be conveniently rewritten as a *string* of length 3 with value 5:

 $\mathbf{e}_3 \xrightarrow{A_5} \mathbf{e}_2 \xrightarrow{A_5} \mathbf{e}_1 \xrightarrow{A_5} \mathbf{0}$

Since $A_5\mathbf{e}_1 = \mathbf{0}$, \mathbf{e}_1 is an eigenvector with value 5. $(A_5)^2\mathbf{e}_2 = \mathbf{0}$ and $(A_5)^3\mathbf{e}_3 = \mathbf{0}$ and so \mathbf{e}_2 and \mathbf{e}_3 are called generalized eigenvectors. Although there is no basis of eigenvectors, there is a basis of generalized eigenvectors.

Definition Define $A_{\lambda} = A - \lambda I$. Call $\mathbf{v} \neq \mathbf{0}$ a generalized eigenvector with value λ for A if $(A_{\lambda})^{p}\mathbf{v} = \mathbf{0}$ for some natural p. If p = 1, \mathbf{v} is called an eigenvector.

§3. Proof of Jordan's Theorem

Introduction to the proof Although there is no basis of eigenvectors, we show there is a basis of generalized eigenvectors. More specifically we find a collection of strings:



such that the $\mathbf{w}_{i,j}$'s form a basis. With respect to this basis the matrix of A is in Jordan normal form because the *i*-th string generates a Jordan block J_{λ_i,n_i} , and conversely a Jordan matrix generates a collection of strings of basis vectors. Accordingly we concern ourselves with generating strings of basis vectors.

The proof we give is due to Filippov (see Linear Algebra and Its Applications by G. Strang).

Proof Let A be n by n. The case n = 1 is trivial. By "strong" induction, assume every smaller size matrix can be put in Jordan normal form, which by the comments above, amounts to the existence of strings.

A has an eigenvector \mathbf{v} with value λ . Since $A_{\lambda}\mathbf{v} = \mathbf{0}$, we have $r \stackrel{\text{def}}{=} \dim \operatorname{Ker} A_{\lambda} > 0$. By the Rank+Nullity Theorem (or directly, since the row reduced form of A_{λ} has r free variables there must be n - r pivots) we have dim Range $A_{\lambda} = n - r < n$. Call $W = \operatorname{Range} A_{\lambda}$.

Step 1 $A_{\lambda}(W) \subseteq W$ so A_{λ} induces a transformation $T: W \to W$. Since dim(W) < n, the matrix of T is of smaller size than n so by induction there are strings:

$$\mathbf{w}_{1,n_{1}} \xrightarrow{A_{\lambda_{1}}} \cdots \xrightarrow{A_{\lambda_{1}}} \mathbf{w}_{1,1} \xrightarrow{A_{\lambda_{1}}} \mathbf{0}$$

$$\vdots \qquad \vdots \qquad \vdots \qquad \vdots$$

$$\mathbf{w}_{k,n_{k}} \xrightarrow{A_{\lambda_{k}}} \cdots \xrightarrow{A_{\lambda_{k}}} \mathbf{w}_{k,1} \xrightarrow{A_{\lambda_{k}}} \mathbf{0}$$

where the $\mathbf{w}_{i,j}$'s form a basis for W — here we used the fact that $(A_{\lambda})_{\mu_i} = A_{\lambda+\mu_i} \stackrel{\text{def}}{=} A_{\lambda_i}$. Step 2 Let $q = \dim(W \cap \operatorname{Ker} A_{\lambda})$. Since $\mathbf{w}_{j,1} \in \operatorname{Ker} A_{\lambda_j}$, q of the above strings are A_{λ} strings, say the first $q: \lambda_j = \lambda$ for $1 \leq j \leq q$. At the other end of these strings, $\mathbf{w}_{j,n_j} \in W = \operatorname{Range} A_{\lambda}$ so there are \mathbf{y}_j with $\mathbf{y}_j \xrightarrow{A_{\lambda}} \mathbf{w}_{j,n_j}$ for $1 \leq j \leq q$.

Step 3 Since Ker A_{λ} is r dimensional and meets W on a q dimensional subspace, some r - q dimensional subspace Z of Ker A_{λ} meets W only at **0**. Let $\mathbf{z}_1, \ldots, \mathbf{z}_{r-q}$ be a basis for Z. This gives q + (n-r) + (r-q) = n vectors in strings:

It suffices to show they are linearly independent, so assume

$$\sum_{i} a_i \mathbf{y}_i + \sum_{i,j} b_{ij} \mathbf{w}_{i,j} + \sum_{i} c_i \mathbf{z}_i = \mathbf{0}.$$

Applying A_{λ} gives a linear combination, L, in $\mathbf{w}_{i,j}$'s as one can see by referring to the strings above. Using $A_{\lambda_r}\mathbf{w}_{s,r} = \mathbf{w}_{s,r-1}$ together with $A_{\lambda} = A_{\lambda_r} + (\lambda_r - \lambda)I$ shows $A_{\lambda}\mathbf{w}_{s,r} = \mathbf{w}_{s,r-1} + (\lambda_r - \lambda)\mathbf{w}_{s,r}$, hence the coefficient of the \mathbf{w}_{j,n_j} for $1 \leq j \leq q$ in linear combination L is a_j . By linear independence of the $\mathbf{w}_{i,j}$'s we obtain $a_j = 0$. So

$$\sum_{i,j} b_{ij} \mathbf{w}_{i,j} + \sum_i c_i \mathbf{z}_i = \mathbf{0}.$$

But $\sum_{i,j} b_{ij} \mathbf{w}_{i,j} = \mathbf{0}$ and $\sum_i c_i \mathbf{z}_i = \mathbf{0}$ since W and Z meet only at **0**. By linear independence in W and Z, $b_{ij} = 0$ and $c_i = 0$.