### Graph morphisms

Question: What makes Cayley graphs special among graphs?

**Examples:** Draw the Cayley graph  $\Gamma(\mathbb{Z}_6, \{1\})$  and the Cayley graph  $\Gamma(\mathbb{Z} \times \mathbb{Z}, \{(0, 1), (1, 0)\})$ :

In a way Cayley graphs are the "pearls" among graphs. They are very regular. We already know that locally every vertex has the same "neighbourhood":

**Lemma 1** Let  $G = (G, \cdot)$  be a group with neutral element  $e \in G$  and  $S \subset G$  a generating set, i.e.  $\langle S \rangle = G$ , such that #S = n for some  $n \in \mathbb{N}$ . Let  $\Gamma = \Gamma(G, S)$  be the corresponding Cayley graph. Then

$$\operatorname{val}(g) = \operatorname{val}(e) = 2n \text{ for all } g \in G = V(\Gamma).$$

# proof HW 3

#### Questions

- 1.) How can we define maps between graphs?
- 2.) When are two graphs equal?

To answer these questions properly we first recall the definition of the Cartesian product.

Note 2 (Cartesian product) If A and B are sets then

$$A \times B = \{(a, b) \mid a \in A, b \in B\}$$

is the **Cartesian product** of A and B.

We have:  $(a_1, b_1) = (a_2, b_2) \Leftrightarrow a_1 = a_2$  and  $b_1 = b_2$ . For two functions  $f : A \to C$  and  $g : B \to D$  we define by  $f \times g : A \times B \to C \times D$  the function given by

$$(a,b) \to f \times g(a,b) := (f(a),g(b))$$
 for all  $a \in A, b \in B$ .

It follows that:

**Lemma 3** f and g are both bijective  $\Leftrightarrow f \times g$  bijective.

# proof HW 7

**Example** Let  $A = C = (\mathbb{Z}_3, +_3)$  and  $B = D = (\mathbb{Z}_4, +_4)$ . Let f and g be the maps defined by

$$f(a) := a +_3 1$$
 and  $g(b) := b +_4 2$ .

Draw a picture of  $A \times B = \mathbb{Z}_3 \times \mathbb{Z}_4$  in a coordinate system on the left and a picture of  $C \times D = \mathbb{Z}_3 \times \mathbb{Z}_4$  on the right and visualize the map  $f \times g$ .

To define a proper map  $f: \Gamma \to \tilde{\Gamma}$  between graphs we must assure that the image  $f(\Gamma')$  of a subgraph  $\Gamma'$  of  $\Gamma$  is a subgraph of  $\tilde{\Gamma}$ . Such a map is called a **graph morphism**. This condition is guaranteed if we use the following definition.

**Definition 4** (Graph morphism) Let  $\Gamma = (V, E, \delta)$  and  $\tilde{\Gamma} = (\tilde{V}, \tilde{E}, \tilde{\delta})$  be two graphs. Then

- 1.) a (graph) morphism  $f: \Gamma \to \tilde{\Gamma}$  is a pair of two maps  $f = (f_V, f_E)$ 
  - $-f_V: V \to \tilde{V}$  and  $f_E: E \to \tilde{E}$ , such that
  - for all  $e \in E$  we have: if  $\delta(e) = (u, w)$  then  $\tilde{\delta}(f_E(e)) = (f_V(u), f_V(w))$  or shortly

$$\tilde{\delta}(f_E(e)) = f_V \times f_V(\delta(e)).$$

This means that if two vertices are connected by an edge e then the images of the vertices must be connected to  $f_E(e)$  and the map f preserves starting and endpoints.

2.) f is called a (graph) isomorphism, if there is a graph morphism  $g: \Gamma \to \tilde{\Gamma}$ , such that

$$f \circ g = id_{\tilde{\Gamma}}$$
 and  $g \circ f = id_{\Gamma}$ 

An isomorphism  $f: \Gamma \to \Gamma$  is called a (graph) automorphism.

Note 1.) If it is clear from the context we skip the subscript in  $f_V(v)$  and  $f_E(e)$  and just write f(v) and f(e).

2.) The condition  $\delta(f_E(e)) = f_V \times f_V(\delta(e))$  can be interpreted as: if an edge e goes to f(e) then its endpoints must follow or also if a vertex v goes to f(v) then its attached edges must follow.

#### Examples

**Theorem 5** 1.) The composition of two graph morphisms is again a graph morphism. 2.)  $f: \Gamma \to \tilde{\Gamma}$  isomorphism  $\Leftrightarrow f_V$  and  $f_E$  are both bijective.

**proof of Theorem 5** 1.) For  $i \in \{1, 2, 3\}$  let  $\Gamma_i = (V_i, E_i, \delta_i)$  be a graph and let  $f = (f_{V_1}, f_{E_1})$ :  $\Gamma_1 \to \Gamma_2$  and  $g = (g_{V_2}, g_{E_2}) : \Gamma_2 \to \Gamma_3$  be two graph morphisms. Then clearly

$$g \circ f = (g_{V_2} \circ f_{V_1}, g_{E_2} \circ f_{E_1})$$

is a pair of maps, such that  $g_{V_2} \circ f_{V_1} : V_1 \to V_3$  and  $g_{E_2} \circ f_{E_1} : E_1 \to E_3$ . It remains to show the second condition. We have for all  $e_1 \in E_1, e_2 \in E_2$ :

$$\delta_2(f_{E_1}(e_1)) = f_{V_1} \times f_{V_1}(\delta_1(e_1)) \text{ and } \delta_3(g_{E_2}(e_2)) = g_{V_2} \times g_{V_2}(\delta_2(e_2))$$

Hence for  $e_2 = f_{E_1}(e_1)$  we obtain first with second equation and then with the first equation above

$$\delta_3(g_{E_2} \circ f_{E_1}(e_1)) = g_{V_2} \times g_{V_2}(\delta_2(f_{E_1}(e_1))) = g_{V_2} \times g_{V_2} \circ f_{V_1} \times f_{V_1}(\delta_1(e_1)) = g_{V_2} \circ f_{V_1} \times g_{V_2} \circ f_{V_1}(\delta_1(e_1)).$$

This shows that the second condition for a morphism in **Definition 4** is also satisfied.

2.) To show the second part of **Theorem 5** we show the equivalence.

" $\Rightarrow$ " We recall from **Chapter 5** that

a)  $f_V: V \to \tilde{V}$  bijective  $\Leftrightarrow \exists f_V^{-1}: \tilde{V} \to V$ , such that

$$f_V^{-1} \circ f_V = id_V$$
 and  $f_V \circ f_V^{-1} = id_{\tilde{V}}$ 

b)  $f_E: E \to \tilde{E}$  bijective  $\Leftrightarrow \exists f_E^{-1}: \tilde{E} \to E$ , such that

$$f_E^{-1} \circ f_E = id_E$$
 and  $f_E \circ f_E^{-1} = id_{\tilde{E}}$ 

As  $f \circ g = id_{\tilde{V}}$  and  $g \circ f = id_V$  we have that  $f_V^{-1} = g_{\tilde{V}}$  and  $f_E^{-1} = g_{\tilde{E}}$  and  $f_V$  and  $f_E$  are bijective.

" $\Leftarrow$ " Conversely if  $f_V$  and  $f_E$  are bijective then there exist the inverse maps  $f_V^{-1} : \tilde{V} \to V$ and  $f_E^{-1} : \tilde{E} \to E$  and we can set  $g = f^{-1} = (f_V^{-1}, f_E^{-1})$ . It remains to show that  $f^{-1}$  satisfies the second condition, i.e. for all  $\tilde{e} \in \tilde{V}$  we have

$$\delta(f_E^{-1}(\tilde{e})) = f_V^{-1} \times f_V^{-1}(\tilde{\delta}(\tilde{e})).$$
(1)

We know that

$$\tilde{e} = f_E(e) \Leftrightarrow e = f_E^{-1}(\tilde{e}) \text{ for all } \tilde{e} \in \tilde{E}, e \in E$$
 (2)

$$\tilde{v} = f_V(v) \Leftrightarrow v = f_V^{-1}(\tilde{v}) \text{ for all } \tilde{v} \in \tilde{V}, v \in V$$
(3)

$$\delta(f_E(e)) = f_V \times f_V(\delta(e)). \tag{4}$$

By the definition of  $f_V \times f_V$  we also have that  $(f_V \times f_V)^{-1} = f_V^{-1} \times f_V^{-1}$ . To prove (1) we use (2) and set  $e = f_E^{-1}(\tilde{e})$  in (1):

$$\delta(f_E^{-1}(\tilde{e})) = \delta(e) = (f_V^{-1} \times f_V^{-1}) \circ (f_V \times f_V)(\delta(e)) \stackrel{(4)}{=} (f_V^{-1} \times f_V^{-1})\tilde{\delta}(f_E(e)) \stackrel{(2)}{=} (f_V^{-1} \times f_V^{-1})\tilde{\delta}(\tilde{e})$$

This proves our statement (1). This concludes the proof of **Theorem 5**.