

### Cayley graphs

**Aim:** To understand how groups look like, we represent them by a graph, the so called **Cayley graph**.

**Definition 1** (Graph) A **graph** is an ordered triplet  $\Gamma = (V, E, \delta)$ , such that

- $V = V(\Gamma)$ : set of **vertices** or **nodes** of  $\Gamma$
- $E = E(\Gamma)$ : set of **edges** of  $\Gamma$
- $\delta : E \rightarrow V \times V = \{(u, v) \mid u, v \in V\}$ : the **gluing map** that assigns to each edge an ordered pair of vertices.

If  $\delta(e) = (u, v) = (o(e), t(e))$ , then we call

- $u = o(e)$  the **origin** of the edge  $e \in E$
- $v = t(e)$  the **terminus** of the edge  $e \in E$

**Note:** As the edges have an origin and terminus, they are oriented. We can think of the edges as arrows, where the tip is at the terminus.

**Example:** Let  $V = \{v_1, v_2, v_3, v_4\}$  be four vertices (points) and  $E = \{e_1, e_2, e_3, e_4\}$  four edges (arrows). Draw your own graph  $\Gamma$  with these edges and vertices. Then use the picture to describe the gluing function  $\delta$ .

#### Notation

- we often abbreviate  $(V, E, \delta)$  by  $(V, E)$ . However, we need  $\delta$  as there may be multiple edges between two vertices. Otherwise we could use a simpler definition.
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- two vertices  $u, v$  are called **adjacent** if they are connected by an edge. In this case we write shortly  $u \sim v$ .
- similarly two edges  $e, f$  are called **adjacent** if they have a common vertex. In this case we also write  $e \sim f$ .
- a **loop** is an edge that connects a single vertex.
  
- a **simple graph** is a graph that has no loops pairs of vertices connected by multiple edges.
- the **valency**  $\text{val}(v)$  of a vertex  $v$  is the number of edges connected to a vertex, where a loop is counted twice. Informally this is the number of "half-edges" connected to a vertex.

A subgraph is a part of a graph that is also a graph. To assure that it is indeed a graph, we must make sure that its edges are connected to vertices inside the subgraph:

**Definition 2** (Subgraph) If  $\Gamma = (V, E, \delta)$  is a graph, then  $\Gamma' = (V', E')$  is a **subgraph** of  $\Gamma$  if

- 1.)  $V' \subset V$  and  $E' \subset E$
- 2.) for all  $e' \in E'$  we have that  $\delta(e') \subset V' \times V'$

**Example**

**Definition 3** (Cayley graph) If  $G = (G, \cdot)$  is a group and  $S \subset G$  a generating set, i.e.  $\langle S \rangle = G$ . Then the (directed) graph  $\Gamma = (V, E, \delta)$  defined by

- $V = G$
  - $E = G \times S = \{(g, s) \mid g \in G, s \in S\}$
  - $\delta : G \times S \rightarrow G \times G, \boxed{\delta : (g, s) \mapsto \delta(g, s) = (g, g \cdot s)}$ .
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is the **Cayley graph**  $\Gamma = \Gamma(G, S)$  of  $G$  with respect to  $S$ .

Though this is not part of the definition, we will usually restrict ourselves to the case where the generating set is finite, i.e.  $\boxed{\# S = n}$  for some  $n \in \mathbb{N}$ .

**Examples** Here we assume that  $e$  is the neutral element of  $G$ .

i)  $\Gamma_1 = \Gamma(\{e\}, \{e\})$ , where  $G = \{e\}$  is the group with one element.

ii)  $\Gamma_2 = \Gamma(\mathbb{Z}_5, \{1\})$

iii)  $\Gamma_3 = \Gamma(\mathbb{Z}, \{1\})$

iv) For  $\Gamma_4 = \Gamma(G, S)$ , where  $S = \{s_1, s_2, s_3\}$ . Draw all edges connected to the vertex  $e$ .

**Exercise**

v)  $\Gamma_5 = \Gamma(\mathbb{Z}, \{2, 3\})$

vi)  $\Gamma_5 = \Gamma(\mathbb{Z}_5, \{0, 1, 2\})$

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