# **Linear Transformations**

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## The Null Space and the Range of a Linear Transformation

- Let  $T: V \to W$  be a linear transformation.
- The **null space** (or **kernel**) N(T) of T is the set of all vectors x in V such that T(x) = 0.
- The **range** (or **image**) R(T) of T is the subset of W consisting of all images (under T) of vectors in V.

1

**Theorem.** Let *V* and *W* be vector spaces, and let  $T : V \to W$  be linear. If  $\beta = \{v_1, v_2, \dots, v_n\}$  is a basis for *V*, then

$$R(T) =$$
**span** $(\{T(v_1), T(v_2), \dots, T(v_n)\}).$ 

## Nullity and Rank

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- Suppose that N(T) and R(T) are finite-dimensional.
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## Nullity and Rank

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- Suppose that N(T) and R(T) are finite-dimensional.
- The **nullity** of *T*, denoted nullity(*T*), is defined to be the dimension of *N*(*T*).
- The **rank** of *T*, denoted rank(T), is defined to be the dimension of R(T).

#### **Dimension Theorem**

**Theorem.** Let *V* and *W* be vector spaces, and let  $T : V \rightarrow W$  be linear. If *V* is finite dimensional, then

nullity(T) + rank(T) = dim(V).

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**Theorem.** Let V and W be vector spaces of equal (finite) dimension, and let  $T : V \rightarrow W$  be linear. Then the following are equivalent:

- 1. *T* is one-to-one.
- **2.**T is onto.
- 3. rank(T) = dim(V).

## Linear Transformations are Determined by the Values on a Basis

**Theorem.** Let *V* and *W* be vector spaces over *F*, and suppose that  $\{v_1, v_2, \ldots, v_n\}$  is a basis for *V*. For  $w_1, w_2, \ldots, w_n$  in *W*, there exists exactly one linear transformation  $T : V \to W$  such that  $T(v_i) = w_i$  for  $i = 1, 2, \ldots, n$ .

**Corollary.** Let *V* and *W* be vector spaces, and suppose that *V* has a finite basis  $\{v_1, v_2, \ldots, v_n\}$ . If  $U, T : V \to W$  are linear and  $U(v_i) = T(v_i)$  for  $i = 1, 2, \ldots, n$ , then U = T.