Math 23, Spring 2017

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• Second order equation

$$\Rightarrow$$
 y'' = f(t, y, ')

• Second order linear equation

$$\Rightarrow$$
 y'' + p(t)y' + q(t)y = g(t)

Homogeneous equations and initial conditions

Definition

A second order linear equation

y'' + p(t)y' + q(t)y = g(t).

is called **homogeneous** if g(t) = 0.

Otherwise it is called **nonhomogeneous**.

Note that when specifying an IVP for a second-order equation, we have to give two initial conditions, both the value of the y and y':

$$y(t_0) = y_0, \qquad y'(t_0) = y'_0.$$

For example, to solve y'' = f(t) you will need to integrate the f(t) and $\int_{t_0}^t f(s) ds$, thus you will need to deal with two arbitrary constants.

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Theorem 3.2.1

Consider the IVP

y'' + p(t)y' + q(t)y = g(t), $y(t_0) = y_0,$ $y'(t_0) = y'_0$

where p, q, g are continuous on (α, β) and $t_0 \in (\alpha, \beta)$. Then, there is exactly one solution y(t) of this problem, and the solution is defined on the interval (α, β) .

- The IVP has a solution!
- The solution is unique!
- The unique solution is defined (at least) on the interval (α, β) , where is at least twice differentiable

Homogeneous equations with constant coefficients

Definition

To the equation

$$ay'' + by' + cy = 0$$
 $a, b, c\mathbb{R}$

we associate a **characteristic equation**

$$ar^2 + br + c = 0.$$

If the characteristic equation has

- 1. two different real roots $r_1, r_2 \in \mathbb{R} \Rightarrow y = C_1 e^{r_1 t} + C_2 e^{r_2 t}, \ C_1, C_2 \in \mathbb{R}$
- 2. double root $r \in \mathbb{R} \Rightarrow y = C_1 e^{rt} + C_2 t e^{rt}, \ C_1, C_2 \in \mathbb{R}$
- 3. two complex roots $r = \alpha \pm i\beta \Rightarrow y = C_1 e^{\alpha t} \cos(\beta t) + C_2 e^{\alpha t} \sin(\beta t) C_1, C_2 \in \mathbb{R}$

Why?

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If the characteristic equation associated to ay'' + by' + cy = 0 has

- 1. two different real roots $r_1, r_2 \in \mathbb{R} \Rightarrow y = C_1 e^{r_1 t} + C_2 e^{r_2 t}, \ C_1, C_2 \in \mathbb{R}$
- 2. double root $r \in \mathbb{R} \Rightarrow y = C_1 e^{rt} + C_2 t e^{rt}, \ C_1, C_2 \in \mathbb{R}$
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Theorem

If \tilde{r} is a root of the characteristic equation , then $y(t) = e^{\tilde{r}t}$ is a solution.

Corollary

 $ar^2 + bt + c = 0$ has two different roots, r_1 and r_2 , then e^{r_1t} and e^{r_2t} are both solutions.

Theorem 3.2.2

If y_1 and y_2 are solutions of the differential equation

P(t)y'' + Q(t)y' + R(t)y = 0

then the linear combination $c_1y_1 + c_2y_2$ is also a solution for any constants c_1, c_2 .

Corollary

 $ar^2 + bt + c = 0$ has two different roots, r_1 and r_2 , then e^{r_1t} and e^{r_2t} are both solutions. Furthermore, $C_1e^{r_1t} + C_2e^{r_2t}$ is also a solution for any $C_1, C_2 \in \mathbb{R}$.

Question

Can we solve any IVP?

In other words, can we solve ay'' + by' + cy = 0 for any set of initial conditions $y(t_0) = y_0, y'(t_0) = y'_0$?

If so, the solution will be unique! (Why?) In case 1., we need to be able to find C_1 and C_2 such that

$$\begin{cases} C_1 e^{r_1 t_0} + C_2 e^{r_2 t_0} &= y_0 \\ C_1 r_1 e^{r_1 t_0} + C_2 r_2 e^{r_2 t_0} &= y'_0 \end{cases}$$

Can we always do that?

Determinant (p. 148)

$$\begin{cases} \underbrace{C_1}_{x} \underbrace{e^{r_1 t_0}}_{a} + \underbrace{C_2}_{y} \underbrace{e^{r_2 t_0}}_{b} &= \underbrace{y_0}_{e} \\ \underbrace{C_1}_{x} \underbrace{r_1 e^{r_1 t_0}}_{c} + \underbrace{C_2}_{y} \underbrace{r_2 e^{r_2 t_0}}_{d} &= \underbrace{y'_0}_{f} \\ \end{cases} \Leftrightarrow \begin{cases} ax + by &= e \\ cx + dy &= f \end{cases}$$

Solving the RHS algebraically we get

$$x = \frac{1}{ad - bc}(de - bf)$$
$$y = \frac{1}{ad - bc}(af - ce)$$

For generic e and f we need to be able to divide by ad - bc to solve the system.

$$\det \begin{pmatrix} a & b \\ c & d \end{pmatrix} = ad - bc$$

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Determinant

Other way to look at it. Each equation in

$$\begin{cases} ax + by = e \\ cx + dy = f \end{cases}$$

represents a line in the xv-plane.

Thus, we are trying to find where they intersect.

- If det $\begin{pmatrix} a & b \\ c & d \end{pmatrix} \neq 0$, the lines are **not** parallel and there is only one solution. If det $\begin{pmatrix} a & b \\ c & d \end{pmatrix} \neq 0$, the lines are parallel.
 - - The lines are parallel and distinct \rightarrow no solution.
 - Both equations represent the same line \rightarrow infinitely many solutions.

$$\begin{cases} C_1 e^{r_1 t_0} + C_2 e^{r_2 t_0} = y_0 \\ C_1 r_1 e^{r_1 t_0} + C_2 r_2 e^{r_2 t_0} = y'_0 \end{cases} \text{ has a solution if and only if } \det \begin{pmatrix} e^{r_1 t_0} & e^{r_2 t_0} \\ r_1 e^{r_1 t_0} & r_2 e^{r_2 t_0} \end{pmatrix} \neq 0 \\ \det \begin{pmatrix} e^{r_1 t_0} & e^{r_2 t_0} \\ r_1 e^{r_1 t_0} & r_2 e^{r_2 t_0} \end{pmatrix} = \underbrace{e^{(r_1 + r_2) t_0}}_{\neq 0} \underbrace{(r_1 - r_2)}_{\neq 0} \neq 0$$

Can we generalize this?

Wronkskian

Definition

Let y_1 and y_2 be two solutions of the homogeneous ODE

$$y'' + p(t)y' + q(t)y = 0.$$

The Wronkskian of these solutions is a function in t

$$W(y_1, y_2)(t) := \det \begin{pmatrix} y_1(t) & y_2(t) \\ y_1'(t) & y_2'(t) \end{pmatrix} = y_1(t)y_2'(t) - y_2(t)y_1'(t)$$

Exercise 20 (practice)

$$W(f,g)(t) = t\cos t - \sin t;$$

$$u = f + 3g \text{ and } v = f - g.$$

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Theorem 3.2.3

Let $y_1(t)$ and $y_2(t)$ be two solutions of the homogeneous ODE

y'' + p(t)y' + q(t)y = 0,

that are defined at t_0 . If $W(y_1, y_2)(t_0) \neq 0$, then **every** solution to the initial value problem

$$y(t_0) = y_0, \quad y'(t_0) = y'_0$$

can solved in the form

 $y(t) = C_1 y_1(t) + C_2 y_2(t).$