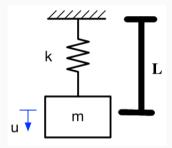
Math 23, Spring 2017

Edgar Costa April 21, 2017

Dartmouth College

- Gravity force = mg
- Spring force $= -k\ell$, where ℓ is the elongation of the spring
- L = the equilibrium position, i.e., mg = KL
- u(t) = the displacement of mass from the equilibrium position, measured downwards
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- Damping/Friction: $F_d = -\gamma u'$ (opposite direction)
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We can also do the same to model electric circuits.

Classification

$$mu'' + \gamma u' + ku = F(t)$$

$$m, k > 0 \text{ and } \gamma \ge 0$$

$$mr^{2} + \gamma r + k = 0 \Rightarrow r = \frac{-\gamma \pm \sqrt{\gamma^{2} - 4km}}{2m}$$

- : $\gamma={\rm 0}~{\rm undamped}$
- + $\gamma > 0$ damped
 - $\cdot \gamma^2 4km < 0$ underdamped
 - $\gamma^2 4km = 0$ critically damped (no oscillation)
 - $\cdot \gamma^2 4km > 0$ overdamped (no oscillation)
- F(t) = 0 free
- $F(t) \neq 0$ and periodic, forced vibration

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$$mu'' + \gamma u' + ku = 0;$$
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• $\gamma^2 - 4km < 0$ undamped or underdamped $\Rightarrow r = \frac{-\gamma \pm \sqrt{\gamma^2 - 4km}}{2m} = -\alpha \pm \omega_0 i$ $u(t) = e^{-\alpha t} (c_1 \cos(\omega_0 t) + c_2 \sin(\omega_0 t)) = \cdots = Ae^{-\alpha t} \cos(\omega_0 t - b)$ u(t) crosses the *t*-axis infinitely many times

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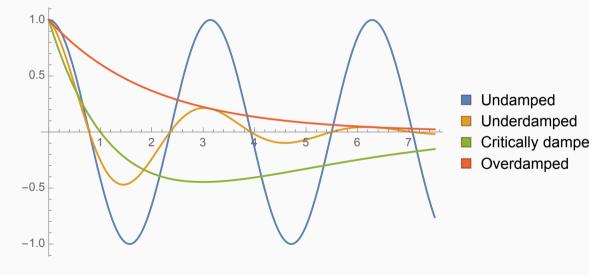
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• $\gamma^2 - 4km > 0$ overdamped, $u(t) = c_1 e^{r_1 t} + c_2 e^{r_2 t}$, with $r_1, r_2 < 0$

A picture is worth a thousand formulas



$$mu'' + \gamma u' + ku = F_0 \cos(\omega_0 t)$$

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$$mu'' + \gamma u' + ku = F_0 \cos(\omega_0 t)$$
$$m, k > 0 \text{ and } \gamma > 0$$

$$\begin{split} u(t) &= u_H(t) + u_p(t) \\ &\text{If } \gamma > 0, \\ & \lim_{t \to +\infty} u_H(t) = 0 \\ & u_p(t) = A\cos(\omega_0 t) + B\sin(\omega_0 t) \end{split}$$

Thus, regardless of the IVP if $\gamma > 0$ $u(t) \simeq u_p(t)$ as $t \to +\infty$.

Resonance

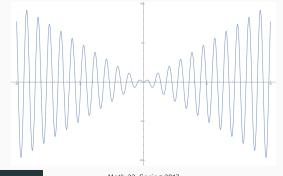
 $\omega_0 = k/m$ and $\gamma = 0$ (for simplicity)

$$mu'' + ku = F_0 \cos(\omega_0 t)$$
$$u_H(t) = A \cos(\omega_0 t - b), \quad u_p(t) = tB \cos(\omega_0 t - b_0)$$

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$$\begin{aligned} mu'' + \gamma u' + ku &= F_0 \cos(\omega t) \\ m, k > 0 \text{ and } \gamma > 0 \\ u_p(t) &= R \cos(wt - b_0) \end{aligned}$$

Picking $\omega^2 &= \frac{k}{m} \left(1 - \frac{\gamma^2}{2mk}\right)$ and γ small, we get $R \simeq \frac{F_0 m}{\gamma \sqrt{k/m}} \left(1 + \frac{\gamma^2}{8mk}\right). \end{aligned}$

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Thus, if $\gamma \sqrt{k/m} \to 0$, the amplitude of particular solution goes to $+\infty$.

A mass weighing 3 lb stretches a spring 3 in. If the mass is pushed upward, contracting the spring a distance of 1 in, and then set in motion with a downward velocity of 2 ft/s, and if there is no damping, find the position u of the mass at any time t. Determine the frequency, period, amplitude, and phase of the motion.