

Lecture 14

Math 22 Summer 2017 July 19, 2017



- §4.3 Bases of a vector space
- Midterm1 tonight 6pm 8pm in Kemeny 008







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A concise way to think about a basis is as a minimal spanning set.

§4.3 Examples of bases





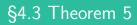
•
$$\mathcal{B} = \{\mathbf{e}_1, \dots, \mathbf{e}_n\}$$
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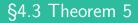




- $\mathcal{B} = \{\mathbf{e}_1, \dots, \mathbf{e}_n\}$ is a basis of \mathbb{R}^n .
- $\mathcal{B} = \{1, t, t^2, \dots, t^n\}$ is a basis of \mathbb{P}_n .
- Let B = {v₁, v₂, v₃} be a set of 3 vectors in ℝ³. How can we check if B is a basis?









Suppose we have a spanning set and we want to get a basis.





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What's the proof?









$$A = \begin{bmatrix} 1 & 0 & 3 & 0 & 11 & 0 & 0 \\ 0 & 1 & 2 & 0 & 7 & 0 & 0 \\ 0 & 0 & 0 & 1 & 5 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 1 & 13 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}.$$





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What is a basis for $\mathrm{Col}A$? Eliminate columns that are linear combinations of the others.

What changes if A is not in RREF?

§4.3 Example continued





Now consider the matrix B whose RREF is A.

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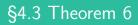


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Let's organize these observations in a theorem...







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The pivot columns of a matrix form a basis for the column space.



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- $T : \mathbb{R}^n \to \mathbb{R}^n$ onto implies T one-to-one. **True**
- A invertible implies $A\mathbf{x} = \mathbf{0}$ has a nontrivial solution.



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- $T : \mathbb{R}^n \to \mathbb{R}^n$ onto implies T one-to-one. **True**
- A invertible implies $A\mathbf{x} = \mathbf{0}$ has a nontrivial solution. False



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