



Lecture 07

Math 22 Summer 2017
July 05, 2017



- ▶ Answers to classwork06 from last time
- ▶ §1.9 more about linear maps

Answers to classwork06





<https://math.dartmouth.edu/~m22x17/section2lectures/classwork06ans.pdf>



<https://math.dartmouth.edu/~m22x17/section2lectures/classwork06ans.pdf>

OK, enough smiley faces for one day.



<https://math.dartmouth.edu/~m22x17/section2lectures/classwork06ans.pdf>

OK, enough smiley faces for one day.

Can you make any observations about how the matrix A relates to where the vectors \mathbf{e}_1 and \mathbf{e}_2 are mapped by T ?



<https://math.dartmouth.edu/~m22x17/section2lectures/classwork06ans.pdf>

OK, enough smiley faces for one day.

Can you make any observations about how the matrix A relates to where the vectors \mathbf{e}_1 and \mathbf{e}_2 are mapped by T ?

We summarize this in the following theorem.

§1.9 Theorem 10



§1.9 Theorem 10



Theorem

Let $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear map.



Theorem

Let $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear map.

Then there exists a unique $m \times n$ matrix A such that

$$T(\mathbf{x}) = A\mathbf{x} \quad \text{for all } \mathbf{x} \text{ in } \mathbb{R}^n.$$



Theorem

Let $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear map.

Then there exists a unique $m \times n$ matrix A such that

$$T(\mathbf{x}) = A\mathbf{x} \quad \text{for all } \mathbf{x} \text{ in } \mathbb{R}^n.$$

Moreover, we have that

$$A = [T(\mathbf{e}_1) \ \cdots \ T(\mathbf{e}_n)].$$



Theorem

Let $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear map.

Then there exists a unique $m \times n$ matrix A such that

$$T(\mathbf{x}) = A\mathbf{x} \quad \text{for all } \mathbf{x} \text{ in } \mathbb{R}^n.$$

Moreover, we have that

$$A = [T(\mathbf{e}_1) \cdots T(\mathbf{e}_n)].$$

The matrix A is called the **standard matrix for T** .



Theorem

Let $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear map.

Then there exists a unique $m \times n$ matrix A such that

$$T(\mathbf{x}) = A\mathbf{x} \quad \text{for all } \mathbf{x} \text{ in } \mathbb{R}^n.$$

Moreover, we have that

$$A = [T(\mathbf{e}_1) \ \cdots \ T(\mathbf{e}_n)].$$

The matrix A is called the **standard matrix for T** .

Sometimes we write $[T]$ to indicate the standard matrix for T .

§1.9 Proof of Theorem 10



§1.9 Proof of Theorem 10



Proof.

§1.9 Proof of Theorem 10



Proof.

First write $\mathbf{x} = x_1\mathbf{e}_1 + \cdots + x_n\mathbf{e}_n$.

§1.9 Proof of Theorem 10



Proof.

First write $\mathbf{x} = x_1\mathbf{e}_1 + \cdots + x_n\mathbf{e}_n$. Then apply linearity:

§1.9 Proof of Theorem 10



Proof.

First write $\mathbf{x} = x_1\mathbf{e}_1 + \cdots + x_n\mathbf{e}_n$. Then apply linearity:

$$\begin{aligned}T(x_1\mathbf{e}_1 + \cdots + x_n\mathbf{e}_n) &= x_1T(\mathbf{e}_1) + \cdots + x_nT(\mathbf{e}_n) \\&= \begin{bmatrix} T(\mathbf{e}_1) & \cdots & T(\mathbf{e}_n) \end{bmatrix} \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} \\&= A\mathbf{x}.\end{aligned}$$

§1.9 Proof of Theorem 10



Proof.

First write $\mathbf{x} = x_1\mathbf{e}_1 + \cdots + x_n\mathbf{e}_n$. Then apply linearity:

$$\begin{aligned}T(x_1\mathbf{e}_1 + \cdots + x_n\mathbf{e}_n) &= x_1T(\mathbf{e}_1) + \cdots + x_nT(\mathbf{e}_n) \\ &= \begin{bmatrix} T(\mathbf{e}_1) & \cdots & T(\mathbf{e}_n) \end{bmatrix} \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} \\ &= A\mathbf{x}.\end{aligned}$$

What about “uniqueness”?



§1.9 Examples



§1.9 Examples

Let $\lambda \in \mathbb{R}$.



§1.9 Examples



Let $\lambda \in \mathbb{R}$.

Find the standard matrix for the map $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ defined by

$$T(\mathbf{x}) = \lambda \mathbf{x}.$$

§1.9 Examples



Let $\lambda \in \mathbb{R}$.

Find the standard matrix for the map $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ defined by $T(\mathbf{x}) = \lambda\mathbf{x}$.

Solution:

$$[T] = \begin{bmatrix} \lambda & 0 \\ 0 & \lambda \end{bmatrix}$$

§1.9 Examples



Let $\lambda \in \mathbb{R}$.

Find the standard matrix for the map $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ defined by $T(\mathbf{x}) = \lambda\mathbf{x}$.

Solution:

$$[T] = \begin{bmatrix} \lambda & 0 \\ 0 & \lambda \end{bmatrix}$$

Let $\theta \in \mathbb{R}$.

§1.9 Examples



Let $\lambda \in \mathbb{R}$.

Find the standard matrix for the map $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ defined by $T(\mathbf{x}) = \lambda\mathbf{x}$.

Solution:

$$[T] = \begin{bmatrix} \lambda & 0 \\ 0 & \lambda \end{bmatrix}$$

Let $\theta \in \mathbb{R}$.

Find the standard matrix for the map $R_\theta : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ which rotates \mathbb{R}^2 about the origin θ radians anti-clockwise.

§1.9 Examples



Let $\lambda \in \mathbb{R}$.

Find the standard matrix for the map $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ defined by $T(\mathbf{x}) = \lambda\mathbf{x}$.

Solution:

$$[T] = \begin{bmatrix} \lambda & 0 \\ 0 & \lambda \end{bmatrix}$$

Let $\theta \in \mathbb{R}$.

Find the standard matrix for the map $R_\theta : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ which rotates \mathbb{R}^2 about the origin θ radians anti-clockwise.

Solution:

$$[R_\theta] = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix}$$

§1.9 injectivity and surjectivity



§1.9 injectivity and surjectivity



Definition

Let $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$.

§1.9 injectivity and surjectivity



Definition

Let $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$.

We say T is **onto** (or **surjective**) if every $\mathbf{b} \in \mathbb{R}^m$ is the image of *at least one* $\mathbf{x} \in \mathbb{R}^n$.

§1.9 injectivity and surjectivity



Definition

Let $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$.

We say T is **onto** (or **surjective**) if every $\mathbf{b} \in \mathbb{R}^m$ is the image of *at least one* $\mathbf{x} \in \mathbb{R}^n$.

We say T is **one-to-one** (or **injective**) if every $\mathbf{b} \in \mathbb{R}^m$ is the image of *at most one* $\mathbf{x} \in \mathbb{R}^n$.

§1.9 injectivity and surjectivity



Definition

Let $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$.

We say T is **onto** (or **surjective**) if every $\mathbf{b} \in \mathbb{R}^m$ is the image of *at least one* $\mathbf{x} \in \mathbb{R}^n$.

We say T is **one-to-one** (or **injective**) if every $\mathbf{b} \in \mathbb{R}^m$ is the image of *at most one* $\mathbf{x} \in \mathbb{R}^n$.

If T is both injective and surjective we say that T is a **bijection**.

§1.9 injectivity and surjectivity



Definition

Let $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$.

We say T is **onto** (or **surjective**) if every $\mathbf{b} \in \mathbb{R}^m$ is the image of *at least one* $\mathbf{x} \in \mathbb{R}^n$.

We say T is **one-to-one** (or **injective**) if every $\mathbf{b} \in \mathbb{R}^m$ is the image of *at most one* $\mathbf{x} \in \mathbb{R}^n$.

If T is both injective and surjective we say that T is a **bijection**.

How can we algorithmically determine if linear maps have these properties?

§1.9 Example



§1.9 Example



Let T have standard matrix

$$A = \begin{bmatrix} 1 & 2 & -3 & 5 \\ 0 & -7 & 11 & -13 \\ 0 & 0 & 0 & 17 \end{bmatrix}.$$

§1.9 Example



Let T have standard matrix

$$A = \begin{bmatrix} 1 & 2 & -3 & 5 \\ 0 & -7 & 11 & -13 \\ 0 & 0 & 0 & 17 \end{bmatrix}.$$

What is the domain/codomain of T ?

§1.9 Example



Let T have standard matrix

$$A = \begin{bmatrix} 1 & 2 & -3 & 5 \\ 0 & -7 & 11 & -13 \\ 0 & 0 & 0 & 17 \end{bmatrix}.$$

What is the domain/codomain of T ? $T : \mathbb{R}^4 \rightarrow \mathbb{R}^3$.

§1.9 Example



Let T have standard matrix

$$A = \begin{bmatrix} 1 & 2 & -3 & 5 \\ 0 & -7 & 11 & -13 \\ 0 & 0 & 0 & 17 \end{bmatrix}.$$

What is the domain/codomain of T ? $T : \mathbb{R}^4 \rightarrow \mathbb{R}^3$.

Is T onto?

§1.9 Example



Let T have standard matrix

$$A = \begin{bmatrix} 1 & 2 & -3 & 5 \\ 0 & -7 & 11 & -13 \\ 0 & 0 & 0 & 17 \end{bmatrix}.$$

What is the domain/codomain of T ? $T : \mathbb{R}^4 \rightarrow \mathbb{R}^3$.

Is T onto? Yes!

§1.9 Example



Let T have standard matrix

$$A = \begin{bmatrix} 1 & 2 & -3 & 5 \\ 0 & -7 & 11 & -13 \\ 0 & 0 & 0 & 17 \end{bmatrix}.$$

What is the domain/codomain of T ? $T : \mathbb{R}^4 \rightarrow \mathbb{R}^3$.

Is T onto? Yes! No matter what $\mathbf{b} \in \mathbb{R}^3$ we choose, the augmented matrix $[A|\mathbf{b}]$ corresponds to a consistent system.

§1.9 Example



Let T have standard matrix

$$A = \begin{bmatrix} 1 & 2 & -3 & 5 \\ 0 & -7 & 11 & -13 \\ 0 & 0 & 0 & 17 \end{bmatrix}.$$

What is the domain/codomain of T ? $T : \mathbb{R}^4 \rightarrow \mathbb{R}^3$.

Is T onto? Yes! No matter what $\mathbf{b} \in \mathbb{R}^3$ we choose, the augmented matrix $[A|\mathbf{b}]$ corresponds to a consistent system.

Is T one-to-one?

§1.9 Example



Let T have standard matrix

$$A = \begin{bmatrix} 1 & 2 & -3 & 5 \\ 0 & -7 & 11 & -13 \\ 0 & 0 & 0 & 17 \end{bmatrix}.$$

What is the domain/codomain of T ? $T : \mathbb{R}^4 \rightarrow \mathbb{R}^3$.

Is T onto? Yes! No matter what $\mathbf{b} \in \mathbb{R}^3$ we choose, the augmented matrix $[A|\mathbf{b}]$ corresponds to a consistent system.

Is T one-to-one? No!

§1.9 Example



Let T have standard matrix

$$A = \begin{bmatrix} 1 & 2 & -3 & 5 \\ 0 & -7 & 11 & -13 \\ 0 & 0 & 0 & 17 \end{bmatrix}.$$

What is the domain/codomain of T ? $T : \mathbb{R}^4 \rightarrow \mathbb{R}^3$.

Is T onto? Yes! No matter what $\mathbf{b} \in \mathbb{R}^3$ we choose, the augmented matrix $[A|\mathbf{b}]$ corresponds to a consistent system.

Is T one-to-one? No! Let $\mathbf{b} \in \mathbb{R}^3$.

§1.9 Example



Let T have standard matrix

$$A = \begin{bmatrix} 1 & 2 & -3 & 5 \\ 0 & -7 & 11 & -13 \\ 0 & 0 & 0 & 17 \end{bmatrix}.$$

What is the domain/codomain of T ? $T : \mathbb{R}^4 \rightarrow \mathbb{R}^3$.

Is T onto? Yes! No matter what $\mathbf{b} \in \mathbb{R}^3$ we choose, the augmented matrix $[A|\mathbf{b}]$ corresponds to a consistent system.

Is T one-to-one? No! Let $\mathbf{b} \in \mathbb{R}^3$. How many solutions does the linear system $[A|\mathbf{b}]$ have?

§1.9 Example



Let T have standard matrix

$$A = \begin{bmatrix} 1 & 2 & -3 & 5 \\ 0 & -7 & 11 & -13 \\ 0 & 0 & 0 & 17 \end{bmatrix}.$$

What is the domain/codomain of T ? $T : \mathbb{R}^4 \rightarrow \mathbb{R}^3$.

Is T onto? Yes! No matter what $\mathbf{b} \in \mathbb{R}^3$ we choose, the augmented matrix $[A|\mathbf{b}]$ corresponds to a consistent system.

Is T one-to-one? No! Let $\mathbf{b} \in \mathbb{R}^3$. How many solutions does the linear system $[A|\mathbf{b}]$ have? Infinitely many since x_3 is free.

§1.9 Example



§1.9 Example



Let T have standard matrix

$$A = \begin{bmatrix} 1 & 2 & -3 & 5 \\ 0 & -7 & 11 & -13 \\ 0 & 0 & 19 & 17 \\ 0 & 0 & 0 & 23 \\ 0 & 0 & 0 & 0 \end{bmatrix}.$$

§1.9 Example



Let T have standard matrix

$$A = \begin{bmatrix} 1 & 2 & -3 & 5 \\ 0 & -7 & 11 & -13 \\ 0 & 0 & 19 & 17 \\ 0 & 0 & 0 & 23 \\ 0 & 0 & 0 & 0 \end{bmatrix}.$$

What is the domain/codomain of T ?

§1.9 Example



Let T have standard matrix

$$A = \begin{bmatrix} 1 & 2 & -3 & 5 \\ 0 & -7 & 11 & -13 \\ 0 & 0 & 19 & 17 \\ 0 & 0 & 0 & 23 \\ 0 & 0 & 0 & 0 \end{bmatrix}.$$

What is the domain/codomain of T ? $T : \mathbb{R}^4 \rightarrow \mathbb{R}^5$.

§1.9 Example



Let T have standard matrix

$$A = \begin{bmatrix} 1 & 2 & -3 & 5 \\ 0 & -7 & 11 & -13 \\ 0 & 0 & 19 & 17 \\ 0 & 0 & 0 & 23 \\ 0 & 0 & 0 & 0 \end{bmatrix}.$$

What is the domain/codomain of T ? $T : \mathbb{R}^4 \rightarrow \mathbb{R}^5$.
Is T onto?

§1.9 Example



Let T have standard matrix

$$A = \begin{bmatrix} 1 & 2 & -3 & 5 \\ 0 & -7 & 11 & -13 \\ 0 & 0 & 19 & 17 \\ 0 & 0 & 0 & 23 \\ 0 & 0 & 0 & 0 \end{bmatrix}.$$

What is the domain/codomain of T ? $T : \mathbb{R}^4 \rightarrow \mathbb{R}^5$.

Is T onto? No!

§1.9 Example



Let T have standard matrix

$$A = \begin{bmatrix} 1 & 2 & -3 & 5 \\ 0 & -7 & 11 & -13 \\ 0 & 0 & 19 & 17 \\ 0 & 0 & 0 & 23 \\ 0 & 0 & 0 & 0 \end{bmatrix}.$$

What is the domain/codomain of T ? $T : \mathbb{R}^4 \rightarrow \mathbb{R}^5$.

Is T onto? No! Can you find a $\mathbf{b} \in \mathbb{R}^5$ so that the system $[A|\mathbf{b}]$ is inconsistent?

§1.9 Example



Let T have standard matrix

$$A = \begin{bmatrix} 1 & 2 & -3 & 5 \\ 0 & -7 & 11 & -13 \\ 0 & 0 & 19 & 17 \\ 0 & 0 & 0 & 23 \\ 0 & 0 & 0 & 0 \end{bmatrix}.$$

What is the domain/codomain of T ? $T : \mathbb{R}^4 \rightarrow \mathbb{R}^5$.

Is T onto? No! Can you find a $\mathbf{b} \in \mathbb{R}^5$ so that the system $[A|\mathbf{b}]$ is inconsistent?

Is T one-to-one?

§1.9 Example



Let T have standard matrix

$$A = \begin{bmatrix} 1 & 2 & -3 & 5 \\ 0 & -7 & 11 & -13 \\ 0 & 0 & 19 & 17 \\ 0 & 0 & 0 & 23 \\ 0 & 0 & 0 & 0 \end{bmatrix}.$$

What is the domain/codomain of T ? $T : \mathbb{R}^4 \rightarrow \mathbb{R}^5$.

Is T onto? No! Can you find a $\mathbf{b} \in \mathbb{R}^5$ so that the system $[A|\mathbf{b}]$ is inconsistent?

Is T one-to-one? Yes!

§1.9 Example



Let T have standard matrix

$$A = \begin{bmatrix} 1 & 2 & -3 & 5 \\ 0 & -7 & 11 & -13 \\ 0 & 0 & 19 & 17 \\ 0 & 0 & 0 & 23 \\ 0 & 0 & 0 & 0 \end{bmatrix}.$$

What is the domain/codomain of T ? $T : \mathbb{R}^4 \rightarrow \mathbb{R}^5$.

Is T onto? No! Can you find a $\mathbf{b} \in \mathbb{R}^5$ so that the system $[A|\mathbf{b}]$ is inconsistent?

Is T one-to-one? Yes! Since there are no free variables, the system $[A|\mathbf{b}]$ never has more than one solution.

§1.9 Example



Let T have standard matrix

$$A = \begin{bmatrix} 1 & 2 & -3 & 5 \\ 0 & -7 & 11 & -13 \\ 0 & 0 & 19 & 17 \\ 0 & 0 & 0 & 23 \\ 0 & 0 & 0 & 0 \end{bmatrix}.$$

What is the domain/codomain of T ? $T : \mathbb{R}^4 \rightarrow \mathbb{R}^5$.

Is T onto? No! Can you find a $\mathbf{b} \in \mathbb{R}^5$ so that the system $[A|\mathbf{b}]$ is inconsistent?

Is T one-to-one? Yes! Since there are no free variables, the system $[A|\mathbf{b}]$ never has more than one solution.

Can you see an easy way to define a linear transformation T that is a *bijection*?

§1.9 Theorem 11



§1.9 Theorem 11



Theorem

Let $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear map.

§1.9 Theorem 11



Theorem

Let $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear map. T is one-to-one if and only if $T(\mathbf{x}) = \mathbf{0}$ has only the trivial solution.

§1.9 Theorem 11



Theorem

Let $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear map. T is one-to-one if and only if $T(\mathbf{x}) = \mathbf{0}$ has only the trivial solution.

Proof.

First note that $T(\mathbf{0}) = \mathbf{0}$.

§1.9 Theorem 11



Theorem

Let $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear map. T is one-to-one if and only if $T(\mathbf{x}) = \mathbf{0}$ has only the trivial solution.

Proof.

First note that $T(\mathbf{0}) = \mathbf{0}$. What's the proof?

§1.9 Theorem 11



Theorem

Let $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear map. T is one-to-one if and only if $T(\mathbf{x}) = \mathbf{0}$ has only the trivial solution.

Proof.

First note that $T(\mathbf{0}) = \mathbf{0}$. What's the proof?

(\Rightarrow):

§1.9 Theorem 11



Theorem

Let $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear map. T is one-to-one if and only if $T(\mathbf{x}) = \mathbf{0}$ has only the trivial solution.

Proof.

First note that $T(\mathbf{0}) = \mathbf{0}$. What's the proof?

(\Rightarrow): Every element in the image has a unique preimage. In particular, so does $\mathbf{0}$.

§1.9 Theorem 11



Theorem

Let $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear map. T is one-to-one if and only if $T(\mathbf{x}) = \mathbf{0}$ has only the trivial solution.

Proof.

First note that $T(\mathbf{0}) = \mathbf{0}$. What's the proof?

(\Rightarrow): Every element in the image has a unique preimage. In particular, so does $\mathbf{0}$.

(\Leftarrow):

§1.9 Theorem 11



Theorem

Let $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear map. T is one-to-one if and only if $T(\mathbf{x}) = \mathbf{0}$ has only the trivial solution.

Proof.

First note that $T(\mathbf{0}) = \mathbf{0}$. What's the proof?

(\Rightarrow): Every element in the image has a unique preimage. In particular, so does $\mathbf{0}$.

(\Leftarrow): Assume $T(\mathbf{x}) = \mathbf{0}$ has only the trivial solution.

§1.9 Theorem 11



Theorem

Let $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear map. T is one-to-one if and only if $T(\mathbf{x}) = \mathbf{0}$ has only the trivial solution.

Proof.

First note that $T(\mathbf{0}) = \mathbf{0}$. What's the proof?

(\Rightarrow): Every element in the image has a unique preimage. In particular, so does $\mathbf{0}$.

(\Leftarrow): Assume $T(\mathbf{x}) = \mathbf{0}$ has only the trivial solution. Now let $\mathbf{b} \in \mathbb{R}^m$ be an arbitrary element in the image of T .

§1.9 Theorem 11



Theorem

Let $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear map. T is one-to-one if and only if $T(\mathbf{x}) = \mathbf{0}$ has only the trivial solution.

Proof.

First note that $T(\mathbf{0}) = \mathbf{0}$. What's the proof?

(\Rightarrow): Every element in the image has a unique preimage. In particular, so does $\mathbf{0}$.

(\Leftarrow): Assume $T(\mathbf{x}) = \mathbf{0}$ has only the trivial solution. Now let $\mathbf{b} \in \mathbb{R}^m$ be an arbitrary element in the image of T . To show T is one-to-one, what must we show?

§1.9 Theorem 11



Theorem

Let $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear map. T is one-to-one if and only if $T(\mathbf{x}) = \mathbf{0}$ has only the trivial solution.

Proof.

First note that $T(\mathbf{0}) = \mathbf{0}$. What's the proof?

(\Rightarrow): Every element in the image has a unique preimage. In particular, so does $\mathbf{0}$.

(\Leftarrow): Assume $T(\mathbf{x}) = \mathbf{0}$ has only the trivial solution. Now let $\mathbf{b} \in \mathbb{R}^m$ be an arbitrary element in the image of T . To show T is one-to-one, what must we show? That \mathbf{b} has a unique preimage.

§1.9 Theorem 11



Theorem

Let $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear map. T is one-to-one if and only if $T(\mathbf{x}) = \mathbf{0}$ has only the trivial solution.

Proof.

First note that $T(\mathbf{0}) = \mathbf{0}$. What's the proof?

(\Rightarrow): Every element in the image has a unique preimage. In particular, so does $\mathbf{0}$.

(\Leftarrow): Assume $T(\mathbf{x}) = \mathbf{0}$ has only the trivial solution. Now let $\mathbf{b} \in \mathbb{R}^m$ be an arbitrary element in the image of T . To show T is one-to-one, what must we show? That \mathbf{b} has a unique preimage. OK, so let \mathbf{u}, \mathbf{v} be arbitrary elements in the preimage of \mathbf{b} .

§1.9 Theorem 11



Theorem

Let $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear map. T is one-to-one if and only if $T(\mathbf{x}) = \mathbf{0}$ has only the trivial solution.

Proof.

First note that $T(\mathbf{0}) = \mathbf{0}$. What's the proof?

(\Rightarrow): Every element in the image has a unique preimage. In particular, so does $\mathbf{0}$.

(\Leftarrow): Assume $T(\mathbf{x}) = \mathbf{0}$ has only the trivial solution. Now let $\mathbf{b} \in \mathbb{R}^m$ be an arbitrary element in the image of T . To show T is one-to-one, what must we show? That \mathbf{b} has a unique preimage. OK, so let \mathbf{u}, \mathbf{v} be arbitrary elements in the preimage of \mathbf{b} . It suffices to show $\mathbf{u} = \mathbf{v}$.

§1.9 Theorem 11



Theorem

Let $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear map. T is one-to-one if and only if $T(\mathbf{x}) = \mathbf{0}$ has only the trivial solution.

Proof.

First note that $T(\mathbf{0}) = \mathbf{0}$. What's the proof?

(\Rightarrow): Every element in the image has a unique preimage. In particular, so does $\mathbf{0}$.

(\Leftarrow): Assume $T(\mathbf{x}) = \mathbf{0}$ has only the trivial solution. Now let $\mathbf{b} \in \mathbb{R}^m$ be an arbitrary element in the image of T . To show T is one-to-one, what must we show? That \mathbf{b} has a unique preimage. OK, so let \mathbf{u}, \mathbf{v} be arbitrary elements in the preimage of \mathbf{b} . It suffices to show $\mathbf{u} = \mathbf{v}$. But

$$\mathbf{0} = \mathbf{b} - \mathbf{b} = T(\mathbf{u}) - T(\mathbf{v}) = T(\mathbf{u} - \mathbf{v}).$$

§1.9 Theorem 11



Theorem

Let $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear map. T is one-to-one if and only if $T(\mathbf{x}) = \mathbf{0}$ has only the trivial solution.

Proof.

First note that $T(\mathbf{0}) = \mathbf{0}$. What's the proof?

(\Rightarrow): Every element in the image has a unique preimage. In particular, so does $\mathbf{0}$.

(\Leftarrow): Assume $T(\mathbf{x}) = \mathbf{0}$ has only the trivial solution. Now let $\mathbf{b} \in \mathbb{R}^m$ be an arbitrary element in the image of T . To show T is one-to-one, what must we show? That \mathbf{b} has a unique preimage. OK, so let \mathbf{u}, \mathbf{v} be arbitrary elements in the preimage of \mathbf{b} . It suffices to show $\mathbf{u} = \mathbf{v}$. But

$$\mathbf{0} = \mathbf{b} - \mathbf{b} = T(\mathbf{u}) - T(\mathbf{v}) = T(\mathbf{u} - \mathbf{v}).$$

Can you see why we are done?



§1.9 Theorem 12



§1.9 Theorem 12



Theorem

Let $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear map with standard matrix A .

§1.9 Theorem 12



Theorem

Let $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear map with standard matrix A . Then:

§1.9 Theorem 12



Theorem

Let $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear map with standard matrix A . Then:

(a) T is onto if and only if the columns of A span \mathbb{R}^m .

§1.9 Theorem 12



Theorem

Let $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear map with standard matrix A . Then:

(a) T is onto if and only if the columns of A span \mathbb{R}^m .

Proof.



Theorem

Let $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear map with standard matrix A . Then:

(a) T is onto if and only if the columns of A span \mathbb{R}^m .

Proof.

The image of T is the span of the columns. □



Theorem

Let $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear map with standard matrix A . Then:

(a) T is onto if and only if the columns of A span \mathbb{R}^m .

Proof.

The image of T is the span of the columns. □

(b) T is one-to-one if and only if the columns of A are linearly independent.



Theorem

Let $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear map with standard matrix A . Then:

(a) T is onto if and only if the columns of A span \mathbb{R}^m .

Proof.

The image of T is the span of the columns. □

(b) T is one-to-one if and only if the columns of A are linearly independent.

Proof.



Theorem

Let $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear map with standard matrix A . Then:

(a) T is onto if and only if the columns of A span \mathbb{R}^m .

Proof.

The image of T is the span of the columns. □

(b) T is one-to-one if and only if the columns of A are linearly independent.

Proof.

We saw that the columns are linearly independent if and only if $A\mathbf{x} = \mathbf{0}$ has only the trivial solution.



Theorem

Let $T : \mathbb{R}^n \rightarrow \mathbb{R}^m$ be a linear map with standard matrix A . Then:

(a) T is onto if and only if the columns of A span \mathbb{R}^m .

Proof.

The image of T is the span of the columns. □

(b) T is one-to-one if and only if the columns of A are linearly independent.

Proof.

We saw that the columns are linearly independent if and only if $A\mathbf{x} = \mathbf{0}$ has only the trivial solution. Now apply previous theorem. □

Classwork





<https://math.dartmouth.edu/~m22x17/section2lectures/classwork07.pdf>