



Lecture 02

Math 22 Summer 2017 Section 2
June 24, 2017

§1.2 Row Reduction and Echelon Forms



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$$\begin{bmatrix} 1 & 0 & 0 & -5 & 4 & 1 & 6 & 1 \\ 0 & 1 & 2 & 5 & 6 & 6 & 8 & 8 \\ 1 & -1 & -1 & -6 & 2 & -2 & 3 & -3 \\ 0 & 1 & 1 & 1 & 3 & 3 & 4 & 5 \\ -1 & 1 & 1 & 6 & -1 & 2 & -2 & 4 \\ 0 & -1 & -2 & -5 & -4 & -6 & -6 & -6 \end{bmatrix} \longrightarrow \begin{bmatrix} 1 & 0 & 0 & -5 & 0 & 1 & 2 & -3 \\ 0 & 1 & 0 & -3 & 0 & 0 & 0 & 2 \\ 0 & 0 & 1 & 4 & 0 & 3 & 1 & 0 \\ 0 & 0 & 0 & 0 & 1 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

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We call this process **row reduction** or **Gaussian elimination**.

§1.2 Leading entries of a matrix



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Definition

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The **leading entry** of a nonzero row is the left-most nonzero entry.

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- ▶ All entries in a column below a leading entry are zero.

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A matrix is in **reduced echelon form** (or **reduced row echelon form**) if it is in echelon form and satisfies two additional conditions:

- ▶ The leading entry in each nonzero row is a 1.
- ▶ Each leading 1 is the only nonzero entry in its column.

§1.2 Pivots





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A **pivot position** in a matrix A is a location in A corresponding to a leading 1 in the reduced row echelon form of A .



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A **pivot** is a nonzero entry in a pivot position.

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- ▶ The reduced echelon form of a matrix is unique.

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- ▶ The reduced echelon form of a matrix is unique.
- ▶ Although an echelon form of a matrix is not unique, the positions of the leading entries does not change regardless of the echelon form.

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4. Consider the submatrix obtained by removing the row and column containing the pivot. Go to the first step and repeat until there is no submatrix left to consider.

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5. Use row operations to create zeros above each pivot.

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Let's do a 2×3 example by hand...

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Computing RREF by hand requires practice (see classwork).

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The variables corresponding to pivot columns (i.e. x_1 and x_2) are called **basic variables**. The other variables (i.e. x_3) are called **free variables**. We can use this description to write the set of solutions *parametrically*...

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The solutions of the linear system on the previous slide can be described as follows.

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This explains the name *parametric* since the solution set is described by the parametric equation of a line in \mathbb{R}^3 .

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i.e. if and only if an echelon form (not necessarily reduced) has no row of the form

$$\begin{bmatrix} 0 & \cdots & 0 & b \end{bmatrix}$$

with $b \neq 0$.

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Theorem

For a consistent system, the solution set is one of the following:

- (a) a unique solution (no free variables)*
- (b) infinitely many solutions (at least one free variable)*