

SOLUTIONS

Your name:

Instructor (please circle):

Alex Barnett

Michael Musty

Math 22 Summer 2017, Homework 5, due Fri July 28 Please show your work, and check your answers. No credit is given for solutions without work or justification.

8 points

(1) Let $A = \begin{bmatrix} 5 & -1 & -3 & 11 \\ -2 & 1 & 0 & -5 \\ 3 & -2 & 1 & 8 \end{bmatrix}$.

row reduce \rightarrow

$$\begin{bmatrix} 2 & -1 & 0 & 5 \\ 10 & -2 & -6 & 22 \\ 6 & -4 & 2 & 16 \end{bmatrix}$$

scaled so can cancel w/o using fractions...

(a) Find a basis for Col A.

$r_2 \leftarrow r_2 - 5r_1$
 $r_3 \leftarrow r_3 - 3r_1$

$$\sim \begin{bmatrix} 2 & -1 & 0 & 5 \\ 0 & 3 & -6 & -3 \\ 0 & -1 & 2 & 1 \end{bmatrix}$$

$$\sim \begin{bmatrix} 2 & -1 & 0 & 5 \\ 0 & 1 & -2 & -1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

↑ ↑
pivot columns are #1, #2: look up these cols in A.

basis = $\left\{ \begin{bmatrix} 5 \\ -2 \\ 3 \end{bmatrix}, \begin{bmatrix} -1 \\ 1 \\ -2 \end{bmatrix} \right\}$

[1 pt]

(b) What is the dimension of the subspace spanned by the columns of A?

↳ ie, Col A.

dim = 2.

[2 pts]

(c) Find a basis for Nul A.

REF is $\begin{bmatrix} 1 & 0 & -1 & 2 \\ 0 & 1 & -2 & -1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$
free: x_3, x_4

Soln. set for homog. lin. sys:

$x_1 = 1x_3 - 2x_4$
 $x_2 = 2x_3 + 1x_4$
 $x_3 = x_3$
 $x_4 = x_4$

so $\vec{x} = \begin{bmatrix} 1 \\ 2 \\ 1 \\ 0 \end{bmatrix} x_3 + \begin{bmatrix} -2 \\ 1 \\ 0 \\ 1 \end{bmatrix} x_4$

Basis = $\left\{ \begin{bmatrix} 1 \\ 2 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -2 \\ 1 \\ 0 \\ 1 \end{bmatrix} \right\}$

[2 pts]

(d) Write, and explain, an inequality satisfied by the dimension of the nullspace of any matrix B formed by deleting rows from A. [Hint: what is a subspace of what?]

hard

Nul A is a subspace of Nul B, because removing linear equations from the list to be satisfied cannot shrink the soln. set.
I.e. $A\vec{x} = \vec{0} \Rightarrow B\vec{x} = \vec{0}$, so $\vec{x} \in \text{Nul } A \Rightarrow \vec{x} \in \text{Nul } B$.
Apply theorem 11 (Ch. 4): $\dim \text{Nul } B \geq \dim \text{Nul } A = 2$.

6 pts (2) Consider a linear transformation $T : V \rightarrow W$ where V is a vector space with basis $B = \{b_1, \dots, b_n\}$ and W is a vector space with basis $C = \{c_1, \dots, c_m\}$.

[3 pts] (a) Let x, y be in V . Prove that $[x+y]_B = [x]_B + [y]_B$. (Here you may use results up to and including the Unique Representation Theorem. Keep in mind V can be any vector space, not necessarily \mathbb{R}^n .)

[See pt of Thm. 8 on p. 221 of book]

$$\begin{aligned} \vec{x} &= c_1 \vec{b}_1 + \dots + c_n \vec{b}_n & \text{where } [\vec{x}]_B &= \begin{bmatrix} c_1 \\ \vdots \\ c_n \end{bmatrix} \\ \vec{y} &= d_1 \vec{b}_1 + \dots + d_n \vec{b}_n & \text{" } [\vec{y}]_B &= \begin{bmatrix} d_1 \\ \vdots \\ d_n \end{bmatrix} \end{aligned}$$

so by vector space axioms, $\vec{x} + \vec{y} = (c_1 + d_1)\vec{b}_1 + \dots + (c_n + d_n)\vec{b}_n$

by the unique rep. thm. (Thm 7) we can read off the coefficients

$$\text{as those of } [\vec{x} + \vec{y}]_B = \begin{bmatrix} c_1 + d_1 \\ \vdots \\ c_n + d_n \end{bmatrix} = \begin{bmatrix} c_1 \\ \vdots \\ c_n \end{bmatrix} + \begin{bmatrix} d_1 \\ \vdots \\ d_n \end{bmatrix} = [\vec{x}]_B + [\vec{y}]_B$$

where vector addition in \mathbb{R}^n is used.

(b) Suppose the map T is onto. What relation between n and m must hold? Prove your answer. [Hint: construct a map from \mathbb{R}^n to \mathbb{R}^m using coordinate maps, then prove that map is onto]

[3 pts]

hard:

$$\text{Let } S : \mathbb{R}^n \rightarrow \mathbb{R}^m, \text{ with } S(\vec{x}) = [T(x_1 \vec{b}_1 + \dots + x_n \vec{b}_n)]_C$$

ie S is composition of: (inverse coord map), then T , then coord map.

$$\text{ie: } \mathbb{R}^n \xrightarrow[\text{inv. coord map}]{[\vec{v}]_B \rightarrow \vec{v}} V \xrightarrow[\text{given}]{T} W \xrightarrow[\text{coord map}]{\vec{w} \rightarrow [\vec{w}]_C} \mathbb{R}^m$$

$\underbrace{\hspace{15em}}_S$

This map S has a standard matrix A , which is $m \times n$.

Since T is onto, and the coord maps are isomorphisms. (§ 4.4),

S is also onto. (This could be proved in more detail: let \vec{y} in \mathbb{R}^m be arbitrary, then $\vec{w} = y_1 \vec{c}_1 + \dots + y_m \vec{c}_m$ is the image of some \vec{v} in V because T is onto. Finally, $[\vec{v}]_B$ exists because the coord map is a map. So \vec{y} is image of $[\vec{v}]_B$ under S , so S is onto.)

The std matrix of any onto map $\mathbb{R}^n \rightarrow \mathbb{R}^m$ must have pivot in every row, so $m \leq n$.

6 pts

[3 pts]

- (3) (a) Recall the standard basis $\{1, t, t^2\}$ for \mathbb{P}_2 . When we express these monomials about a new origin $t = a$, we get the set $\{1, (t-a), (t-a)^2\}$. Prove, for any a , that this set is also a basis for \mathbb{P}_2 . [Hint: you may use that the coordinate map for the standard basis is an isomorphism.]

We use isomorphism to work in \mathbb{R}^3 : $1 \xrightarrow{\text{std. coord map}} \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$

$$(t-a)^2 = t^2 - 2at + a^2$$

$$t-a \rightarrow \begin{bmatrix} -a \\ 1 \\ 0 \end{bmatrix}$$

$$\text{so } (t-a)^2 \rightarrow \begin{bmatrix} a^2 \\ -2a \\ 1 \end{bmatrix}$$

Stack:

$$A = \begin{bmatrix} 1 & -a & a^2 \\ 0 & 1 & -2a \\ 0 & 0 & 1 \end{bmatrix} \text{ is already in REF, showing full rank } \Rightarrow \text{cols. are basis for } \mathbb{R}^3.$$

thus the set was a basis for \mathbb{P}_2 , by isomorphism.

- (b) The subspace $H = \text{Span} \left\{ \begin{bmatrix} 1 \\ 1 \end{bmatrix} \right\}$ is in the span of the vectors $\mathbf{b}_1 = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$ and $\mathbf{b}_2 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$. Explain whether $\{\mathbf{b}_1, \mathbf{b}_2\}$ is a basis for H .

No: $\text{Span}\{\mathbf{b}_1, \mathbf{b}_2\} = \mathbb{R}^2$ the whole plane, which is bigger than H .

Proof: $\begin{bmatrix} 1 \\ 0 \end{bmatrix} \in \text{Span}\{\mathbf{b}_1, \mathbf{b}_2\}$, but $\begin{bmatrix} 1 \\ 0 \end{bmatrix} \notin H$.

So, even though $\{\mathbf{b}_1, \mathbf{b}_2\}$ are Lin. Indep., they are not a basis for H (which happens to be 1-dim).