Your name:

Instructor (please circle): Alex Barnett Michael Musty

Math 22 Summer 2017, Homework 2, due Fri July 7 Please show your work, and check your answers. No credit is given for solutions without work or justification.

(1) Let h be a scalar, and consider the set of three vectors:

$$\mathbf{v}_1 = \begin{bmatrix} 3\\-2\\-4 \end{bmatrix}, \ \mathbf{v}_2 = \begin{bmatrix} -6\\3\\9 \end{bmatrix}, \ \mathbf{v}_3 = \begin{bmatrix} -3\\2(h-1)\\7 \end{bmatrix}.$$

(a) With h = 1/2, is the set linearly independent, and why? If not, give a dependence relation between \mathbf{v}_1 , \mathbf{v}_2 , and \mathbf{v}_3 .

(b) With h = 0, is the set linearly independent, and why? If not, give a dependence relation between \mathbf{v}_1 , \mathbf{v}_2 , and \mathbf{v}_3 .

(2) Consider the following network flow diagram where the numbers indicate known flows, and x_1, x_2, x_3, x_4 indicate unknown flows on their respective edges.



(a) Find the *reduced* echelon form for the corresponding linear system.

(b) If a solution exists, write the *parametric vector form* of the solution set.

(c) Assume all flows are nonnegative. What constraint does this impose on x_3 ?

(3) (a) Let $T: \mathbb{R}^3 \to \mathbb{R}^3$ be a linear transformation defined by

$$T(\mathbf{x}) = x_1 \mathbf{v}_1 + x_2 \mathbf{v}_2 + x_3 \mathbf{v}_3, \quad \text{with}$$
$$\mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}, \quad \mathbf{v}_1 = \begin{bmatrix} 3 \\ -2 \\ 5 \end{bmatrix}, \quad \mathbf{v}_2 = \begin{bmatrix} 4 \\ -3 \\ 1 \end{bmatrix}, \text{ and } \quad \mathbf{v}_3 = \begin{bmatrix} 7 \\ 1 \\ 2 \end{bmatrix}.$$

Find a matrix A such that $T(\mathbf{x}) = A\mathbf{x}$ for every \mathbf{x} in \mathbb{R}^3 . Explain why your answer is correct.

(b) Let \mathbf{p} be any vector in \mathbb{R}^n and let \mathbf{v} be any nonzero vector in \mathbb{R}^n . Consider the line ℓ defined by the parametric equation

$$\mathbf{x} = \mathbf{p} + t\mathbf{v}, \quad t \text{ in } \mathbb{R}.$$

Let $T : \mathbb{R}^n \to \mathbb{R}^n$ be a linear transformation. Show that the image of ℓ under the map T is either a line in \mathbb{R}^n or a single point.