# MATH22 - Linear Algebra with Applications Exam I ANSWERS July 11, 2007

1. (30 points) Define each of the following:

- (a) a linearly independent set
- (b) the span of a set of vectors
- (c) an onto function

## Answer:

(a) A set of vectors  $\{\mathbf{v_1}, \mathbf{v_2}, \dots, \mathbf{v_n}\}$  is linearly independent if the only solution for  $(x_1, x_2, \dots, x_n)$  in the equation

 $x_1\mathbf{v_1} + x_2\mathbf{v_2} + \dots + x_n\mathbf{v_n} = \mathbf{0}$ 

is the trivial solution  $(x_1, x_2, ..., x_n) = (0, 0, ..., 0).$ 

- (b) The span of a set of vectors is the set of all linear combinations of the vectors in that set.
- (c) An onto function is a function whose range and codomain are the same.

2. (30 points) Calculate the inverse of

$$A = \left[ \begin{array}{rrrr} 1 & 0 & 1 \\ 0 & 1 & -1 \\ -1 & 1 & -1 \end{array} \right].$$

Answer:

$$\begin{bmatrix} 1 & 0 & 1 & | & 1 & 0 & 0 \\ 0 & 1 & -1 & | & 0 & 0 \\ -1 & 1 & -1 & | & 0 & 0 \\ 0 & 0 & 1 & | & -1 & | & 0 & 0 \\ 0 & 1 & -1 & | & 0 & 0 \\ 0 & 1 & -1 & | & 0 & 0 \\ 0 & 1 & -1 & | & 0 & 0 \\ 0 & 0 & 1 & | & 1 & -1 & 1 \end{bmatrix} \xrightarrow{R_3 + R_2 \to R_2}_{-R_3 + R_1 \to R_1} \begin{bmatrix} 1 & 0 & 0 & | & 1 & 0 & 1 \\ 0 & 1 & 0 & | & 1 & 0 & 1 \\ 0 & 0 & 1 & | & 1 & -1 & 1 \end{bmatrix},$$

so we have

$$A^{-1} = \left[ \begin{array}{rrr} 0 & 1 & -1 \\ 1 & 0 & 1 \\ 1 & -1 & 1 \end{array} \right].$$

3. (30 points) Solve the following system:

(Hint: Save yourself some time and trouble by using the result of #2.)

## Answer:

This system can be written in the form  $A\mathbf{x} = \mathbf{b}$  as

$$\begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & -1 \\ -1 & 1 & -1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix}.$$

Noting that this coefficient matrix is the same as the matrix A in the previous problem, we have that

$$\mathbf{x} = A^{-1}\mathbf{b} = \begin{bmatrix} 0 & 1 & -1 \\ 1 & 0 & 1 \\ 1 & -1 & 1 \end{bmatrix} \begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \\ 1 \end{bmatrix}.$$

4. (30 points) Find the general solution of the following system:

## Answer:

Using an augmented matrix, we have

This gives that the solution is

$$\begin{cases} x_1 = 2 + 2x_4 - 3x_3 \\ x_2 = 1 + x_4 - x_3 \\ x_3 \text{ is free} \\ x_4 \text{ is free.} \end{cases}$$

5. (40 points) Let A and B be  $n \times n$  matrices. Prove:  $(A - B)(A + B) = A^2 - B^2$  if and only if A commutes with B.

### Answer:

*Proof.* Let A and B be as given. We have that

$$(A - B)(A + B) = AA - BA + AB - BB = A^{2} - B^{2} + AB - BA.$$
 (1)

If A and B commute, AB - BA = 0, and (1) simplifies to  $(A - B)(A + B) = A^2 - B^2$ . On the other hand, if A and B do not commute,  $AB - BA \neq 0$ , in which case

$$(A - B)(A + B) - (A^2 - B^2) = AB - BA \neq 0$$

and so  $(A - B)(A + B) \neq A^2 - B^2$ .

6. (40 points) TRUE/FALSE (You need not show your work on these problems):

(a) For  $n \times n$  matrices A, B, and C,

$$A(B+C) = BA + CA.$$

(b) If AB = BA for the matrices A and B, then

$$A^T B^T = B^T A^T$$

(c) 
$$E = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 1 & 1 & 0 \end{bmatrix}$$
 is an elementary matrix.

(d) The mapping

$$T: \qquad \mathbb{R}^3 \rightarrow \mathbb{R}^3$$
$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} \mapsto \begin{bmatrix} x_1 \\ x_2 \\ -x_3 \end{bmatrix}$$

is a linear transformation.

(e) If A is the standard matrix for the linear transformation of  $\mathbb{R}^2$  which maps an arbitrary vector  $\mathbf{x} \mapsto -2\mathbf{x}$ , then  $A_{12} = 0$ .

### Answer:

- (a) False.  $A(B+C) = AB + AC \neq BA + CA$  in general.
- (b) True. If AB = BA, then  $(AB)^T = (BA)^T$ , i.e.  $B^T A^T = A^T B^T$ .
- (c) False. To get this matrix from  $I_3$  requires at least 2 row operations, while an elementary matrix is derived from a single operation.
- (d) True.

$$T(c\mathbf{x} + d\mathbf{y}) = T\left( \begin{bmatrix} cx_1 + dy_1 \\ cx_2 + y_2 \\ cx_3 + dy_3 \end{bmatrix} \right) = \begin{bmatrix} cx_1 + dy_1 \\ cx_2 + y_2 \\ -cx_3 - dy_3 \end{bmatrix} = c \begin{bmatrix} x_1 \\ x_2 \\ -x_3 \end{bmatrix} + d \begin{bmatrix} y_1 \\ y_2 \\ -y_3 \end{bmatrix}$$
$$= cT(\mathbf{x}) + dT(\mathbf{y}).$$

(e) True. The standard matrix for this transformation is  $\begin{bmatrix} -2 & 0 \\ 0 & -2 \end{bmatrix}$ .

**7.** (**0** points) BONUS: Show that the transpose of an elementary matrix is an elementary matrix.

## Answer:

Looking at the three types of operations represented by an elementary matrix E, we have:

- (a) Multiplying a row by a nonzero constant. Here, the transpose of E is the same as the matrix itself, so it is clearly elementary.
- (b) Switching one row with another. Here, the transpose of E is again the same as the matrix itself, so once again, it is elementary.
- (c) Adding a nonzero multiple of one row to another. Suppose we add  $kR_i + R_j \to R_j$ for some  $k \neq 0$ . The resulting elementary matrix E has the same elements as the identity matrix with the lone exception that  $E_{ji} = k \neq 0$ . Taking the transpose creates a matrix F with the same elements as the identity matrix with the lone exception that  $F_{ij} = k$ . However, this is the same as the elementary matrix obtained by the operation  $kR_j + R_i \to R_i$ , and so  $F = E^T$  is elementary as well.