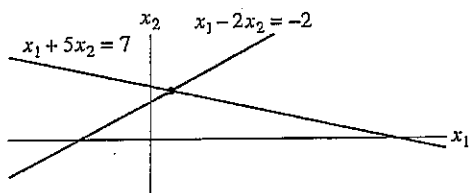


1.1 EXERCISES

Solve each system in Exercises 1–4 by using elementary row operations on the equations or on the augmented matrix. Follow the systematic elimination procedure described in this section.

1. $x_1 + 5x_2 = 7$
 $-2x_1 - 7x_2 = -5$
2. $2x_1 + 4x_2 = -4$
 $5x_1 + 7x_2 = 11$
3. Find the point (x_1, x_2) that lies on the line $x_1 + 5x_2 = 7$ and on the line $x_1 - 2x_2 = -2$. See the figure.



4. Find the point of intersection of the lines $x_1 - 5x_2 = 1$ and $3x_1 - 7x_2 = 5$.

Consider each matrix in Exercises 5 and 6 as the augmented matrix of a linear system. State in words the next two elementary row operations that should be performed in the process of solving the system.

5.
$$\begin{bmatrix} 1 & -4 & 5 & 0 & 7 \\ 0 & 1 & -3 & 0 & 6 \\ 0 & 0 & 1 & 0 & 2 \\ 0 & 0 & 0 & 1 & -5 \end{bmatrix}$$

6.
$$\begin{bmatrix} 1 & -6 & 4 & 0 & -1 \\ 0 & 2 & -7 & 0 & 4 \\ 0 & 0 & 1 & 2 & -3 \\ 0 & 0 & 3 & 1 & 6 \end{bmatrix}$$

In Exercises 7–10, the augmented matrix of a linear system has been reduced by row operations to the form shown. In each case, continue the appropriate row operations and describe the solution set of the original system.

7.
$$\begin{bmatrix} 1 & 7 & 3 & -4 \\ 0 & 1 & -1 & 3 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & -2 \end{bmatrix}$$

8.
$$\begin{bmatrix} 1 & -4 & 9 & 0 \\ 0 & 1 & 7 & 0 \\ 0 & 0 & 2 & 0 \end{bmatrix}$$

9.
$$\begin{bmatrix} 1 & -1 & 0 & 0 & -4 \\ 0 & 1 & -3 & 0 & -7 \\ 0 & 0 & 1 & -3 & -1 \\ 0 & 0 & 0 & 2 & 4 \end{bmatrix}$$

10.
$$\begin{bmatrix} 1 & -2 & 0 & 3 & -2 \\ 0 & 1 & 0 & -4 & 7 \\ 0 & 0 & 1 & 0 & 6 \\ 0 & 0 & 0 & 1 & -3 \end{bmatrix}$$

Solve the systems in Exercises 11–14.

11. $x_2 + 4x_3 = -5$
 $x_1 + 3x_2 + 5x_3 = -2$
 $3x_1 + 7x_2 + 7x_3 = 6$

12. $x_1 - 3x_2 + 4x_3 = -4$
 $3x_1 - 7x_2 + 7x_3 = -8$
 $-4x_1 + 6x_2 - x_3 = 7$

13. $x_1 - 3x_3 = 8$
 $2x_1 + 2x_2 + 9x_3 = 7$
 $x_2 + 5x_3 = -2$

14. $x_1 - 3x_2 = 5$
 $-x_1 + x_2 + 5x_3 = 2$
 $x_2 + x_3 = 0$

Determine if the systems in Exercises 15 and 16 are consistent. Do not completely solve the systems.

15. $x_1 + 3x_3 = 2$
 $x_2 - 3x_4 = 3$
 $-2x_2 + 3x_3 + 2x_4 = 1$
 $3x_1 + 7x_4 = -5$

16. $x_1 - 2x_4 = -3$
 $2x_2 + 2x_3 = 0$
 $x_3 + 3x_4 = 1$
 $-2x_1 + 3x_2 + 2x_3 + x_4 = 5$

17. Do the three lines $x_1 - 4x_2 = 1$, $2x_1 - x_2 = -3$, and $-x_1 - 3x_2 = 4$ have a common point of intersection? Explain.

18. Do the three planes $x_1 + 2x_2 + x_3 = 4$, $x_2 - x_3 = 1$, and $x_1 + 3x_2 = 0$ have at least one common point of intersection? Explain.

In Exercises 19–22, determine the value(s) of h such that the matrix is the augmented matrix of a consistent linear system.

19.
$$\begin{bmatrix} 1 & h & 4 \\ 3 & 6 & 8 \end{bmatrix}$$

21.
$$\begin{bmatrix} 1 & 3 & -2 \\ -4 & h & 8 \end{bmatrix}$$

20.
$$\begin{bmatrix} 1 & h & -3 \\ -2 & 4 & 6 \end{bmatrix}$$

22.
$$\begin{bmatrix} 2 & -3 & h \\ -6 & 9 & 5 \end{bmatrix}$$

In Exercises 23 and 24, key statements from this section are either quoted directly, restated slightly (but still true), or altered in some way that makes them false in some cases. Mark each statement True or False, and *justify* your answer. (If true, give the approximate location where a similar statement appears, or refer to a definition or theorem. If false, give the location of a statement that has been quoted or used incorrectly, or cite an example that shows the statement is not true in all cases.) Similar true/false questions will appear in many sections of the text.

23. a. Every elementary row operation is reversible.
 b. A 5×6 matrix has six rows.
 c. The solution set of a linear system involving variables x_1, \dots, x_n is a list of numbers (s_1, \dots, s_n) that makes each equation in the system a true statement when the values s_1, \dots, s_n are substituted for x_1, \dots, x_n , respectively.
 d. Two fundamental questions about a linear system involve existence and uniqueness.
24. a. Elementary row operations on an augmented matrix never change the solution set of the associated linear system.
 b. Two matrices are row equivalent if they have the same number of rows.
 c. An inconsistent system has more than one solution.
 d. Two linear systems are equivalent if they have the same solution set.
25. Find an equation involving g , h , and k that makes this augmented matrix correspond to a consistent system:
- $$\left[\begin{array}{ccc|c} 1 & -4 & 7 & g \\ 0 & 3 & -5 & h \\ -2 & 5 & -9 & k \end{array} \right]$$
26. Construct three different augmented matrices for linear systems whose solution set is $x_1 = -2$, $x_2 = 1$, $x_3 = 0$.
27. Suppose the system below is consistent for all possible values of f and g . What can you say about the coefficients c and d ? Justify your answer.
- $$x_1 + 3x_2 = f$$
- $$cx_1 + dx_2 = g$$
28. Suppose a , b , c , and d are constants such that a is not zero and the system below is consistent for all possible values of

f and g . What can you say about the numbers a , b , c , and d ? Justify your answer.

$$ax_1 + bx_2 = f$$

$$cx_1 + dx_2 = g$$

In Exercises 29–32, find the elementary row operation that transforms the first matrix into the second, and then find the reverse row operation that transforms the second matrix into the first.

29.
$$\begin{bmatrix} 0 & -2 & 5 \\ 1 & 4 & -7 \\ 3 & -1 & 6 \end{bmatrix}, \begin{bmatrix} 1 & 4 & -7 \\ 0 & -2 & 5 \\ 3 & -1 & 6 \end{bmatrix}$$

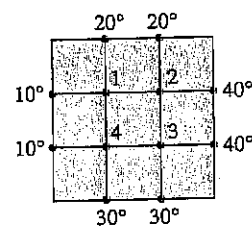
30.
$$\begin{bmatrix} 1 & 3 & -4 \\ 0 & -2 & 6 \\ 0 & -5 & 9 \end{bmatrix}, \begin{bmatrix} 1 & 3 & -4 \\ 0 & 1 & -3 \\ 0 & -5 & 9 \end{bmatrix}$$

31.
$$\begin{bmatrix} 1 & -2 & 1 & 0 \\ 0 & 5 & -2 & 8 \\ 4 & -1 & 3 & -6 \end{bmatrix}, \begin{bmatrix} 1 & -2 & 1 & 0 \\ 0 & 5 & -2 & 8 \\ 0 & 7 & -1 & -6 \end{bmatrix}$$

32.
$$\begin{bmatrix} 1 & 2 & -5 & 0 \\ 0 & 1 & -3 & -2 \\ 0 & -3 & 9 & 5 \end{bmatrix}, \begin{bmatrix} 1 & 2 & -5 & 0 \\ 0 & 1 & -3 & -2 \\ 0 & 0 & 0 & -1 \end{bmatrix}$$

An important concern in the study of heat transfer is to determine the steady-state temperature distribution of a thin plate when the temperature around the boundary is known. Assume the plate shown in the figure represents a cross section of a metal beam, with negligible heat flow in the direction perpendicular to the plate. Let T_1, \dots, T_4 denote the temperatures at the four interior nodes of the mesh in the figure. The temperature at a node is approximately equal to the average of the four nearest nodes—to the left, above, to the right, and below.³ For instance,

$$T_1 = (10 + 20 + T_2 + T_4)/4, \quad \text{or} \quad 4T_1 - T_2 - T_4 = 30$$



³See Frank M. White, *Heat and Mass Transfer* (Reading, MA: Addison-Wesley Publishing, 1991), pp. 145–149.

2. Find the general solution of the system

$$\begin{aligned}x_1 - 2x_2 - x_3 + 3x_4 &= 0 \\ -2x_1 + 4x_2 + 5x_3 - 5x_4 &= 3 \\ 3x_1 - 6x_2 - 6x_3 + 8x_4 &= 2\end{aligned}$$

1.2 EXERCISES

In Exercises 1 and 2, determine which matrices are in reduced echelon form and which others are only in echelon form.

1. a. $\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 1 \end{bmatrix}$ b. $\begin{bmatrix} 1 & 0 & 1 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$

c. $\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$

d. $\begin{bmatrix} 1 & 1 & 0 & 1 & 1 \\ 0 & 2 & 0 & 2 & 2 \\ 0 & 0 & 0 & 3 & 3 \\ 0 & 0 & 0 & 0 & 4 \end{bmatrix}$

2. a. $\begin{bmatrix} 1 & 1 & 0 & 1 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$ b. $\begin{bmatrix} 1 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 1 & 1 \end{bmatrix}$

c. $\begin{bmatrix} 1 & 0 & 0 & 0 \\ 1 & 1 & 0 & 0 \\ 0 & 1 & 1 & 0 \\ 0 & 0 & 1 & 1 \end{bmatrix}$

d. $\begin{bmatrix} 0 & 1 & 1 & 1 & 1 \\ 0 & 0 & 2 & 2 & 2 \\ 0 & 0 & 0 & 0 & 3 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$

Row reduce the matrices in Exercises 3 and 4 to reduced echelon form. Circle the pivot positions in the final matrix and in the original matrix, and list the pivot columns.

3. $\begin{bmatrix} 1 & 2 & 3 & 4 \\ 4 & 5 & 6 & 7 \\ 6 & 7 & 8 & 9 \end{bmatrix}$ 4. $\begin{bmatrix} 1 & 3 & 5 & 7 \\ 3 & 5 & 7 & 9 \\ 5 & 7 & 9 & 1 \end{bmatrix}$

5. Describe the possible echelon forms of a nonzero 2×2 matrix. Use the symbols ■, *, and 0, as in the first part of Example 1.

6. Repeat Exercise 5 for a nonzero 3×2 matrix.

Find the general solutions of the systems whose augmented matrices are given in Exercises 7–14.

7. $\begin{bmatrix} 1 & 3 & 4 & 7 \\ 3 & 9 & 7 & 6 \end{bmatrix}$ 8. $\begin{bmatrix} 1 & 4 & 0 & 7 \\ 2 & 7 & 0 & 10 \end{bmatrix}$

9. $\begin{bmatrix} 0 & 1 & -6 & 5 \\ 1 & -2 & 7 & -6 \end{bmatrix}$ 10. $\begin{bmatrix} 1 & -2 & -1 & 3 \\ 3 & -6 & -2 & 2 \end{bmatrix}$

11. $\begin{bmatrix} 3 & -4 & 2 & 0 \\ -9 & 12 & -6 & 0 \\ -6 & 8 & -4 & 0 \end{bmatrix}$

12. $\begin{bmatrix} 1 & -7 & 0 & 6 & 5 \\ 0 & 0 & 1 & -2 & -3 \\ -1 & 7 & -4 & 2 & 7 \end{bmatrix}$

13. $\begin{bmatrix} 1 & -3 & 0 & -1 & 0 & -2 \\ 0 & 1 & 0 & 0 & -4 & 1 \\ 0 & 0 & 0 & 1 & 9 & 4 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$

14. $\begin{bmatrix} 1 & 2 & -5 & -6 & 0 & -5 \\ 0 & 1 & -6 & -3 & 0 & 2 \\ 0 & 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix}$

Exercises 15 and 16 use the notation of Example 1 for matrices in echelon form. Suppose each matrix represents the augmented matrix for a system of linear equations. In each case, determine if the system is consistent. If the system is consistent, determine if the solution is unique.

15. a. $\begin{bmatrix} \blacksquare & * & * & * \\ 0 & \blacksquare & * & * \\ 0 & 0 & \blacksquare & 0 \end{bmatrix}$

b. $\begin{bmatrix} 0 & \blacksquare & * & * & * \\ 0 & 0 & \blacksquare & * & * \\ 0 & 0 & 0 & 0 & \blacksquare \end{bmatrix}$

16. a.
$$\begin{bmatrix} \blacksquare & * & * \\ 0 & \blacksquare & * \\ 0 & 0 & 0 \end{bmatrix}$$

b.
$$\begin{bmatrix} \blacksquare & * & * & * & * \\ 0 & 0 & \blacksquare & * & * \\ 0 & 0 & 0 & \blacksquare & * \end{bmatrix}$$

In Exercises 17 and 18, determine the value(s) of h such that the matrix is the augmented matrix of a consistent linear system.

17.
$$\begin{bmatrix} 2 & 3 & h \\ 4 & 6 & 7 \end{bmatrix}$$

18.
$$\begin{bmatrix} 1 & -3 & -2 \\ 5 & h & -7 \end{bmatrix}$$

In Exercises 19 and 20, choose h and k such that the system has (a) no solution, (b) a unique solution, and (c) many solutions. Give separate answers for each part.

19.
$$\begin{aligned} x_1 + hx_2 &= 2 \\ 4x_1 + 8x_2 &= k \end{aligned}$$

20.
$$\begin{aligned} x_1 + 3x_2 &= 2 \\ 3x_1 + hx_2 &= k \end{aligned}$$

In Exercises 21 and 22, mark each statement True or False. Justify each answer.⁴

21. a. In some cases, a matrix may be row reduced to more than one matrix in reduced echelon form, using different sequences of row operations.
 b. The row reduction algorithm applies only to augmented matrices for a linear system.
 c. A basic variable in a linear system is a variable that corresponds to a pivot column in the coefficient matrix.
 d. Finding a parametric description of the solution set of a linear system is the same as solving the system.
 e. If one row in an echelon form of an augmented matrix is $[0 \ 0 \ 0 \ 5 \ 0]$, then the associated linear system is inconsistent.
22. a. The echelon form of a matrix is unique.
 b. The pivot positions in a matrix depend on whether row interchanges are used in the row reduction process.
 c. Reducing a matrix to echelon form is called the *forward phase* of the row reduction process.

⁴True/false questions of this type will appear in many sections. Methods for justifying your answers were described before Exercises 23 and 24 in Section 1.1.

- d. Whenever a system has free variables, the solution set contains many solutions.
 e. A general solution of a system is an explicit description of all solutions of the system.
23. Suppose a 3×5 coefficient matrix for a system has three pivot columns. Is the system consistent? Why or why not?
24. Suppose a system of linear equations has a 3×5 augmented matrix whose fifth column is a pivot column. Is the system consistent? Why (or why not)?
25. Suppose the coefficient matrix of a system of linear equations has a pivot position in every row. Explain why the system is consistent.
26. Suppose the coefficient matrix of a linear system of three equations in three variables has a pivot in each column. Explain why the system has a unique solution.
27. Restate the last sentence in Theorem 2 using the concept of pivot columns: "If a linear system is consistent, then the solution is unique if and only if _____"
28. What would you have to know about the pivot columns in an augmented matrix in order to know that the linear system is consistent and has a unique solution?
29. A system of linear equations with fewer equations than unknowns is sometimes called an *underdetermined system*. Suppose that such a system happens to be consistent. Explain why there must be an infinite number of solutions.
30. Give an example of an inconsistent underdetermined system of two equations in three unknowns.
31. A system of linear equations with more equations than unknowns is sometimes called an *overdetermined system*. Can such a system be consistent? Illustrate your answer with a specific system of three equations in two unknowns.
32. Suppose an $n \times (n + 1)$ matrix is row reduced to reduced echelon form. Approximately what fraction of the total number of operations (flops) is involved in the backward phase of the reduction when $n = 30$? when $n = 300$?

Suppose experimental data are represented by a set of points in the plane. An **interpolating polynomial** for the data is a polynomial whose graph passes through every point. In scientific work, such a polynomial can be used, for example, to estimate values between the known data points. Another use is to create curves for graphical images on a computer screen. One method for finding an interpolating polynomial is to solve a system of linear equations.

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