## Math 22 - Fall 2019 <br> Practice Exam 3

Your name: $\qquad$

Section (please check the box): $\quad \square$ Section 1 (10 hour) $\quad \square$ Section 2 (2 hour)

## INSTRUCTIONS

- Except on clearly indicated short answer problems, you must explain what you are doing, and show your work. You will be graded on your work, not just on your answer.
- It is fine to leave your answer in a form such as $\sqrt{239}$ or $(385)\left(13^{3}\right)$. However, if an expression can be easily simplified (such as $\cos (\pi)$ or $(3-2)$ ), you should simplify it.
- You may use the last page for scrap paper.
- This is a closed book exam. You may not use notes, computing devices (calculators, computers, cell phones, etc.) or any other external resource.


## GOOD LUCK!

(1) Please indicate whether the following statements are TRUE or FALSE.

Circle the correct answer. You do not have to show your work, however thinking about the problem on a scrap paper is recommended.
1.) If $\operatorname{dim}(V)=p$, and if $S$ is a linearly dependent subset of $V$, then $S$ contains more than $p$ vectors.

## TRUE

## FALSE

2.) If $A$ is a $2 \times 4$ matrix, then the corresponding map $T(\mathbf{x})=A \mathbf{x}$ is always onto.

TRUE
FALSE
3.) There exists a $3 \times 5$ matrix whose row space has dimension 2 .

TRUE
FALSE
4.) Let $U$ and $Q$ be two orthogonal matrices. Then $U Q$ is also an orthogonal matrix.

TRUE
FALSE
5.) Let $U$ be an orthogonal matrix. Then the corresponding map $S(\mathbf{x})=U \mathbf{x}$ preserves angles. This means that the angle between two vectors $\mathbf{x}$ and $\mathbf{y}$ is the same as the angle between $S(\mathbf{x})$ and $S(\mathbf{y})$.

TRUE
FALSE
6.) For any two $4 \times 4$ matrices $A$ and $B$, we have $\operatorname{det}(3 A B)=3^{2} \cdot \operatorname{det}(B) \operatorname{det}(A)$.

TRUE
FALSE
7.) Let $A$ be an $m \times n$ matrix. Then $\operatorname{dim}(\operatorname{Col}(A))=\operatorname{dim}\left(\operatorname{Col}\left(A^{T}\right)\right)$.

TRUE
FALSE
8.) Let $\mathbf{v}$ be an eigenvector of the matrix $A$ with eigenvalue $\lambda$ and also of the matrix $B$ with eigenvalue $\mu$. Then $\mathbf{v}$ is an eigenvector of the matrix $A B$.

TRUE
FALSE
9.) Every stochastic matrix $P$ has a unique steady state vector $\mathbf{q}$.

TRUE
FALSE
(2) Consider the following matrices:

$$
A=\left[\begin{array}{lll}
1 & 2 & 3 \\
4 & 5 & 6
\end{array}\right], \quad B=\left[\begin{array}{cc}
7 & 8 \\
9 & 10
\end{array}\right], \quad C=\left[\begin{array}{c}
1 \\
-2
\end{array}\right] .
$$

For each of the following matrix operations, indicate whether the operation is defined. If an expression is undefined, explain why. If an expression is defined, evaluate it.
a) $B A+C$.
b) $B C$.
c) $B+3 I_{2}$
(3) Find the inverse of the following matrix or show that it does not exist.

$$
A=\left[\begin{array}{ccc}
1 & -2 & 1 \\
4 & -7 & 3 \\
-2 & 6 & -4
\end{array}\right]
$$

(4) Consider the three polynomials in $\mathbb{P}_{2}$ :

$$
p_{1}(t)=1+t^{2}, p_{2}(t)=t-3 t^{2}, p_{3}(t)=1+t-3 t^{2} .
$$

a) Use coordinate vectors to show that these polynomials form a basis $B$ of $\mathbb{P}_{2}$.
b) Find $q \in \mathbb{P}_{2}$, such that $[q]_{B}=\left[\begin{array}{c}-1 \\ 1 \\ 2\end{array}\right]$.
(5) Let $H$ and $K$ be subspaces of a vector space $V$. Show that the intersection $H \cap K$ is a subspace of $V$. Then give a counterexample in $\mathbb{R}^{2}$ that the union $H \cup K$ is not, in general, a subspace.
(6) Let

$$
P=\left[\begin{array}{lll}
1 & 0 & 0 \\
1 & 1 & 0 \\
0 & 1 & 1
\end{array}\right] \text { and } \mathbf{v}_{1}=\left[\begin{array}{l}
0 \\
0 \\
1
\end{array}\right], \mathbf{v}_{2}=\left[\begin{array}{c}
0 \\
-1 \\
0
\end{array}\right], \mathbf{v}_{3}=\left[\begin{array}{c}
-1 \\
0 \\
0
\end{array}\right]
$$

a) Find a basis $U=\left\{\mathbf{u}_{1}, \mathbf{u}_{2}, \mathbf{u}_{3}\right\}$ for $\mathbb{R}^{3}$, such that $P=\underset{V \leftarrow U}{P}$ is the change-of-coordinates matrix from $U$ to $V=\left\{\mathbf{v}_{1}, \mathbf{v}_{2}, \mathbf{v}_{3}\right\}$.
b) Find a basis $W=\left\{\mathbf{w}_{1}, \mathbf{w}_{2}, \mathbf{w}_{3}\right\}$, such that $P=\underset{W \leftarrow V}{P}$ is the change-of-coordinates matrix from $V$ to $W$.
c) Find $\underset{W \leftarrow U}{P}$, the change-of-coordinates matrix from $U$ to $W$.
(7) Let $\left.W=\operatorname{Span}\left\{\begin{array}{l}1 \\ 2 \\ 1\end{array}\right],\left[\begin{array}{l}2 \\ 4 \\ 4\end{array}\right]\right\}=\operatorname{Span}\left\{\mathbf{v}_{1}, \mathbf{v}_{2}\right\}$.
a) Find the cosine of the angle between $\mathbf{v}_{1}$ and $\mathbf{v}_{2}$.
b) Find the distance between $\mathbf{v}_{1}$ and $\mathbf{v}_{2}$.
c) Find $W^{\perp}$ and determine the dimension of $W$ and $W^{\perp}$.
(8) Find the equation of the line $y=f(x)=\beta_{0}+\beta_{1} x$ of the least-squares line that fits best the data points

$$
P_{1}=(0,1), P_{2}=(1,1), P_{3}=(2,2) \text { and } P_{4}=(3,2) .
$$

(9) Let
(1)

$$
\mathbf{w}_{1}=\left[\begin{array}{l}
1 \\
0 \\
0 \\
0
\end{array}\right], \quad \mathbf{w}_{2}=\left[\begin{array}{l}
2 \\
1 \\
2 \\
0
\end{array}\right], \quad \mathbf{w}_{3}=\left[\begin{array}{l}
1 \\
2 \\
4 \\
2
\end{array}\right], \quad \text { and } \quad \mathbf{y}=\left[\begin{array}{l}
1 \\
0 \\
0 \\
1
\end{array}\right]
$$

Let $W$ be the subspace of $\mathbb{R}^{4}$ spanned by $\mathbf{w}_{1}, \mathbf{w}_{2}$ and $\mathbf{w}_{3}$.
a) Use the Gram-Schmidt process to find an orthogonal basis of $W$.
b) Find the orthogonal projection of $\mathbf{y}$ onto $W$.
c) Find the minimum of $\|\mathbf{y}-\mathbf{w}\|$ where $\mathbf{w} \in W$.
(10) Let $A$ be the $3 \times 3$ matrix

$$
A=\left[\begin{array}{ccc}
1 & 0 & 0 \\
-5 & 0 & 2 \\
0 & 0 & 1
\end{array}\right]
$$

a) Find the eigenvalues of $A$ and determine their multiplicity.
b) Find a basis of $\mathbb{R}^{3}$ consisting of eigenvectors of $A$.
c) Diagonalize the matrix $A$.
d) Calculate $A^{7}$.
(11) Let $A$ be a $n \times n$ matrix that is diagonalizable.
a) Give the definition of a diagonalizable matrix.
b) Show that $A^{T}$, the transpose of $A$, has exactly the same eigenvalues as $A$.
c) Let $B=\left\{\mathbf{b}_{1}, \mathbf{b}_{2}, \ldots, \mathbf{b}_{n}\right\}$ be a basis of eigenvectors for $A$. Find a basis of eigenvectors for $A^{T}$.
(This page is intentionally left blank in case you need extra space for any of the problems. If you use this page for a particular problem, it is essential that you make a note on the page where the problem appears, indicating that your work is continued here.)

