# Math 22 – Linear Algebra and its applications

- Lecture 17 -

**Instructor:** Bjoern Muetzel

# **GENERAL INFORMATION**

- **Office hours:** Tu 1-3 pm, **Th**, Sun **2-4 pm** in **KH 229**
- **Tutorial:** Tu, **Th**, Sun **7-9 pm** in **KH 105**
- <u>Homework 5:</u> due today at 4 pm outside KH 008. Please divide into the parts A, B, C and D and write your name on each part.
- **<u>Project:</u>** Meeting next weekend!
- Midterm 2: Friday Nov 1 at 4 pm in Carpenter 013



4.5



FIFTH EDITION

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#### • <u>Summary:</u>

- The number **n** of basis vectors of a vector space V is an invariant. It is called the **dimension of** V
- 2.) If the dimension n of a vector space is known then we can find a basis by finding a spanning set or finding a linearly independent set of n vectors.

### **GEOMETRIC INTERPRETATION**

- **Reminder:** A basis of a vector space V is a linearly independent set that spans V.
- **Theorem 9:** If a vector space V has a basis  $B = \{b_1, ..., b_n\}$ , then any set in V containing more than n vectors must be linearly dependent.
- **Theorem 10:** If a vector space V has a basis of n vectors, then every basis of V must consist of exactly n vectors.

**Proof:** <u>Idea for Theorem 9</u>: As  $V \cong \mathbb{R}^n$  we can use the coordinate map  $[\cdot]_B = T_B : V \to \mathbb{R}^n, x \mapsto T_B(x) = [x]_B$ and do all calculations in  $\mathbb{R}^n$ .

Definition: If V is spanned by a finite set, then V is said to be finite-dimensional, and the dimension of V, written as dim V, is the number of vectors in a basis for V.

dim V = # (basis vectors of V)

- The dimension of the zero vector space **{0}** is defined to be zero.
- If V is not spanned by a finite set, then V is said to be **infinitedimensional**.

• **Example 3:** Find the dimension of the subspace

$$H = \begin{cases} \begin{bmatrix} a - 3b + 6c \\ 5a + 4d \\ b - 2c - d \\ 5d \end{bmatrix} : a, b, c, d \text{ in } \mathbb{R} \end{cases}$$

- Theorem 11: Let *H* be a subspace of a finite-dimensional vector space *V*. Any linearly independent set S in *H* can be expanded, if necessary, to a basis for *H*.
- Proof: <u>Idea</u>: If the set S does not span H, then we can add a vector u from H that is not in span S. {S ∪ u} is linearly independent.
- Consequence: Let *H* be a subspace of a finite-dimensional vector space *V*. Then  $\dim H \leq \dim V$
- **Proof:** A basis B of H is linearly independent. By **Theorem 9** the basis B can not have more vectors than dim *V*. Hence dim  $H \le \dim V$ .

How can we complete a basis  $B = \{b_1, ..., b_k\}$  of a subspace H in  $\mathbb{R}^n$  to a basis of  $\mathbb{R}^n$ ?

**Solution:** Let  $E = \{e_1, ..., e_n\}$  be the standard basis of  $\mathbb{R}^n$ .

Write B in matrix form B=[b<sub>1</sub>, ..., b<sub>k</sub>]. B has a pivot in every column.
 Now bring B<sup>T</sup> into echelon form U<sup>T</sup>. U<sup>T</sup> has a pivot in every row.
 For any non-pivot column j of U<sup>T</sup> add a row e<sup>T</sup><sub>j</sub> to U<sup>T</sup>. We call the matrix obtained this way U'<sup>T</sup>.

4.) Then B together with the basis vectors  $\mathbf{e}_i$  from 3.) forms a basis of  $\mathbb{R}^n$ .

**Proof:** 

**Example:** Let 
$$b_1 = \begin{bmatrix} 1 \\ -1 \\ 2 \end{bmatrix}$$
 and  $b_2 = \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}$ .  
Complete  $\{b_1, b_2\}$  to a basis for  $\mathbb{R}^3$ .

- Theorem 12: (Basis theorem) Let V be an n-dimensional vector space, where n ≥ 1. Then
  - 1.) Any linearly independent set of exactly *n* elements in *V* is automatically a basis for *V*.
  - 2.) Any set of exactly *n* elements that spans *V* is automatically a basis for *V*.

 Proof: 1.) Follows from Theorem 11 or "pivot in every 2.) Follows from the Spanning Set Theorem or "pivot in every "

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## **REMINDER: KERNEL AND RANGE**

Definition: Let T: V → W, x ↦ T(x) be a linear transformation.
1.) The kernel (or null space) Nul(T) of such a T is the set of all u in V such that T(u) = 0 in W.
2.) The range T(V) of T is the set of all vectors in W of the form T (x) for some x in V.



# REMINDER: BASES FOR NUL A AND COL A

Theorem 6: Let T: ℝ<sup>n</sup> → ℝ<sup>m</sup> be a linear transformation and let A be the corresponding standard matrix. Then the p pivot columns of A form a basis for

 $T(\mathbb{R}^n) = Col A = \{b \text{ in } \mathbb{R}^m, s. t. As = b \text{ for some } x \text{ in } \mathbb{R}^n \}.$ 

• Warning: The pivot columns of a matrix *A* can only be read from the echelon form U of A. But be careful to use the **pivot** columns of *A* itself for the basis of Col *A*.

#### **Consequence:**

dim T( $\mathbb{R}^n$ ) = dim Col A = p = #(pivot columns of A)

# REMINDER: BASES FOR NUL A AND COL A

We have seen in Lecture 13:

• **Theorem:** Let T:  $\mathbb{R}^n \to \mathbb{R}^m$  be a linear transformation and let *A* be the corresponding standard matrix. If

 $Nul(T) = Nul A = \{x \text{ in } \mathbb{R}^n, Ax=0\}$ 

contains nonzero vectors then a **basis for Nul** *A* consist out of **q** vectors, where **q** equals the **number of non-pivot columns of A**.

• **Reminder:** We can find Nul A explicitly by solving the homogeneous system of linear equations Ax=0.

#### Consequence:

dim Nul(T)= dim Nul A = q = #(non-pivot columns of A)

# THE DIMENSIONS OF NUL A AND COL A

**Consequence:** 

dim Col 
$$A$$
 + dim Nul  $A = n = \dim (\mathbb{R}^n)$  or

dim T( $\mathbb{R}^n$ ) + dim Nul(T) = dim  $\mathbb{R}^n$ 

# DIMENSIONS OF NUL A AND COL A

Example: Let  $T: \mathbb{R}^5 \to \mathbb{R}^3$  be a linear transformation with standard matrix  $A = \begin{bmatrix} -3 & 6 & -1 & 1 & -7 \\ 1 & -2 & 2 & 3 & -1 \\ 2 & -4 & 5 & 8 & -4 \end{bmatrix}$ 

1.) Find a basis for  $T(\mathbb{R}^5) = \text{Col } A$  and determine dim Col A.

- 2.) What is the dimension of Nul A=Nul(T)
- 3.) Find a basis for Nul A and complete this basis to a basis for  $\mathbb{R}^5$