

Math 22 Fall 2004

Linear Algebra with Applications

Class Demo for the Echelon Forms
September 27, 2004

Load the package for doing Linear Algebra

```
> with(Student[LinearAlgebra]):
```

Define a matrix (4 rows, 5 columns) to work with

```
> M := <<0|-1|2|-3|4>,<2|-4|4|3|-10>,<3|-1|-4|0|-5>,<1|-2|2|-1|-3>>;
```

$$M := \begin{bmatrix} 0 & -1 & 2 & -3 & 4 \\ 2 & -4 & 4 & 3 & -10 \\ 3 & -1 & -4 & 0 & -5 \\ 1 & -2 & 2 & -1 & -3 \end{bmatrix}$$

Step 1: Choose column 1 as our pivot column.

We start by transforming it into an echelon form.

Step 2: Select any non-zero entry as a pivot and bring it into the pivot position (to the top)

```
> M := SwapRows(M, 1, 4); # Bring the pivot entry into the 1st row
```

$$M := \begin{bmatrix} 1 & -2 & 2 & -1 & -3 \\ 2 & -4 & 4 & 3 & -10 \\ 3 & -1 & -4 & 0 & -5 \\ 0 & -1 & 2 & -3 & 4 \end{bmatrix}$$

Step 3: Use the row replacement operations to create zeros in all positions below the pivot.

```
> M := AddRow(M, 2, 1, -2); # Make entry below the pivot in row 2 zero
M := AddRow(M, 3, 1, -3); # Make entry below the pivot in row 3 zero
```

$$M := \begin{bmatrix} 1 & -2 & 2 & -1 & -3 \\ 0 & 0 & 0 & 5 & -4 \\ 3 & -1 & -4 & 0 & -5 \\ 0 & -1 & 2 & -3 & 4 \end{bmatrix}$$

$$M := \begin{bmatrix} 1 & -2 & 2 & -1 & -3 \\ 0 & 0 & 0 & 5 & -4 \\ 0 & 5 & -10 & 3 & 4 \\ 0 & -1 & 2 & -3 & 4 \end{bmatrix}$$

Step 4: Repeat Steps 1–3 for the next column

Pivot column is column 2 now. Bring it into an Echelon Form

```
> M := SwapRows(M, 2, 4); # Bring the pivot in the 2nd column to the 2nd row
```

$$M := \begin{bmatrix} 1 & -2 & 2 & -1 & -3 \\ 0 & -1 & 2 & -3 & 4 \\ 0 & 5 & -10 & 3 & 4 \\ 0 & 0 & 0 & 5 & -4 \end{bmatrix}$$

```
> M := AddRow(M, 3, 2, 5); # Make the entries below the pivot zero
```

$$M := \begin{bmatrix} 1 & -2 & 2 & -1 & -3 \\ 0 & -1 & 2 & -3 & 4 \\ 0 & 0 & 0 & -12 & 24 \\ 0 & 0 & 0 & 5 & -4 \end{bmatrix}$$

Column 3 is in the Echelon Form already. Go to column 4.

```
> M := MultiplyRow(M, 3, 1/12); # Scale the row 3 a bit to make our life easier
```

$$M := \begin{bmatrix} 1 & -2 & 2 & -1 & -3 \\ 0 & -1 & 2 & -3 & 4 \\ 0 & 0 & 0 & -1 & 2 \\ 0 & 0 & 0 & 5 & -4 \end{bmatrix}$$

```
> M := AddRow(M, 4, 3, 5); # Make the entries in column 4 below the pivot  
zero
```

$$M := \begin{bmatrix} 1 & -2 & 2 & -1 & -3 \\ 0 & -1 & 2 & -3 & 4 \\ 0 & 0 & 0 & -1 & 2 \\ 0 & 0 & 0 & 0 & 6 \end{bmatrix}$$

The matrix is in the Echelon Form now

Step 5: Starting from the last column, make all the pivots 1 and all the entries above them zero.

```
> M := MultiplyRow(M, 3, -1); # Make the pivot in the 4th column 1
```

$$M := \begin{bmatrix} 1 & -2 & 2 & -1 & -3 \\ 0 & -1 & 2 & -3 & 4 \\ 0 & 0 & 0 & 1 & -2 \\ 0 & 0 & 0 & 0 & 6 \end{bmatrix}$$

```
> M := AddRow(M, 2, 3, 3); # Make the entry above it in row 2 zero  
M := AddRow(M, 1, 3, 1); # Make the entry above it in row 1 zero
```

$$M := \begin{bmatrix} 1 & -2 & 2 & -1 & -3 \\ 0 & -1 & 2 & 0 & -2 \\ 0 & 0 & 0 & 1 & -2 \\ 0 & 0 & 0 & 0 & 6 \end{bmatrix}$$

$$M := \begin{bmatrix} 1 & -2 & 2 & 0 & -5 \\ 0 & -1 & 2 & 0 & -2 \\ 0 & 0 & 0 & 1 & -2 \\ 0 & 0 & 0 & 0 & 6 \end{bmatrix}$$

> M := MultiplyRow(M, 2, -1); # Make the pivot in column 2 1

$$M := \begin{bmatrix} 1 & -2 & 2 & 0 & -5 \\ 0 & 1 & -2 & 0 & 2 \\ 0 & 0 & 0 & 1 & -2 \\ 0 & 0 & 0 & 0 & 6 \end{bmatrix}$$

> M := AddRow(M, 1, 2, 2); # Make the entry above the pivot zero

$$M := \begin{bmatrix} 1 & 0 & -2 & 0 & -1 \\ 0 & 1 & -2 & 0 & 2 \\ 0 & 0 & 0 & 1 & -2 \\ 0 & 0 & 0 & 0 & 6 \end{bmatrix}$$

The matrix is in the reduced Echelon Form now

Conclusion: the original linear system was inconsistent

Modify it: if there were no last row now, the system would be

> M1 := LinearAlgebra[DeleteRow](M, 4);

$$M1 := \begin{bmatrix} 1 & 0 & -2 & 0 & -1 \\ 0 & 1 & -2 & 0 & 2 \\ 0 & 0 & 0 & 1 & -2 \end{bmatrix}$$

This linear system is consistent. It has 1 free variable, $x[3]$, and 3 basis variables, $x[1]$, $x[2]$, and $x[4]$.

Here is the corresponding linear system:

```
> EqSystem := GenerateEquations(M1, [x[1], x[2], x[3], x[4]]);  
EqSystem := [x1 - 2 x3 = -1, x2 - 2 x3 = 2, x4 = -2]
```

Its general solution is

```
> solve(convert(EqSystem, set));  
{x4 = -2, x2 = 2 + 2 x3, x1 = -1 + 2 x3, x3 = x3}
```

The parametric description of the solution set is

```
> LinearSolve(M1);
```

$$\begin{bmatrix} -1 + 2_t0_3 \\ 2 + 2_t0_3 \\ _t0_3 \\ -2 \end{bmatrix}$$