

Generalized Derivative

- Is a generalization of the "normal" derivative in the sense that it approximates the change in the range given a change in the domain.
- If there is any hope at all, the derivative of a function is the derivative matrix, whose entries are the partial derivatives. rows correspond to range variables and columns correspond to domain variables.
- The above matrix may not work because it is possible that simply knowing the change in each of the "co-ordinate" directions is not enough to describe the local behavior of the function.

- If $\mathbf{F} : \mathbb{R}^m \rightarrow \mathbb{R}^n$ is a function. We say that \mathbf{F} is differentiable at a point $\hat{q} = \langle q_1, q_2, \dots, q_m \rangle$ if $\lim_{\hat{h} \rightarrow \hat{0}} \mathbf{F}(\hat{q} + \hat{h}) - \mathbf{F}(\hat{q}) - DF_{\hat{q}} \cdot_{matrix} \hat{h}$ goes to $\hat{0}$ "faster" than \hat{h} does.
- It is sufficient to find that the each component of the difference contains more than 1 power of a component of h in it. So if the difference is $\langle h_1 h_2, 2h_2^2, 0 \rangle$, then that is good enough.
- The derivative approximates the change in the function in the sense that $DF \cdot_{matrix} \hat{a}$ represents the approximate change in the function as you move \hat{a} away from the base point.
- With the above in mind we can say that the velocity in the range [which is a vector] of the image of a path $\mathbf{r}(t)$ in the domain can be found by computing $DF \cdot_{matrix} \mathbf{r}'(t)$.