Math 11 Fall 2016 Section 1 Wednesday, November 9, 2016

First, some important points from the last class:

If S is parametrized by $\vec{r}(u, v)$ for (u, v) in the domain D, f is a scalar function, and F is a vector field:

$$\iint_{S} f \, dS = \iint_{D} f(\vec{r}(u,v)) \underbrace{|\vec{r}_{u} \times \vec{r}_{v}| \, du \, dv}_{dS};$$
$$\iint_{S} F \cdot \vec{n} \, dS = \iint_{S} F \cdot d\vec{S} = \iint_{D} F(\vec{r}(u,v))(\vec{r}_{u} \times \vec{r}_{v}) \, du \, dv.$$

 $\iint_{S} 1 \, dS \text{ is the surface area of } S.$ If f represents the mass density of the surface at a point (say in grams per square meter), then $\iint_{S} f \, dS$ is the total mass of the surface.

The average value of f on S is $\frac{1}{\operatorname{area}(S)} \iint_S f \, dS$.

If F is a fluid flow field, then the surface integral $\iint_S F \cdot \vec{n} \, dS$ represents the rate of flow through the surface S in the direction given by \vec{n} .

If F is an electric field, then the surface integral $\iint_S F \cdot \vec{n} \, dS$ represents the electric flux through S.

You can imagine an infinitely small piece of the surface S, which is the image under \vec{r} of an infinitely small rectangle of dimensions $du \times dv$ in the uv plane:



Theorem (Stokes' Theorem): If S is an oriented piecewise-smooth surface, and ∂S , the positively-oriented boundary of S (counterclockwise around S as viewed from the top of a unit normal vector \vec{n}), is a simple, closed, piecewise smooth curve, and F is a vector field whose components have continuous partial derivatives on some open region containing S, then

$$\iint_{S} (\nabla \times F) \cdot d\vec{S} = \int_{\partial S} F \cdot d\vec{r}.$$

Example: If S is the surface $x^2 + y^2 + 3z^2 = 1$, $z \ge 0$, oriented with \vec{n} pointing upward, and $F(x, y, z) = \langle y, -x, zx^3y^2 \rangle$, evaluate

$$\iint_{S} (\nabla \times F) \cdot d\vec{S}.$$

The boundary of this surface is the unit circle γ in the xy plane, oriented counterclockwise as viewed from above. We can parametrize γ by $\vec{r}(t) = \langle \cos t, \sin t, 0 \rangle$, $0 \leq t \leq 2\pi$, so $d\vec{r} = \langle -\sin t, \cos t, 0 \rangle$. Then, by Stokes' Theorem,

$$\iint_{S} (\nabla \times F) \cdot d\vec{S} = \int_{\gamma} F \cdot d\vec{r} = \int_{0}^{2\pi} \langle \sin t, -\cos t, 0 \rangle \cdot \langle -\sin t, \cos t, 0 \rangle \ dt = \int_{0}^{2\pi} -1 \ dt = -2\pi.$$

Example: If $F(x, y, z) = \langle x^2, 2xy + x, z \rangle$ and γ is the unit circle in the xy plane, oriented counterclockwise as seen from above, find $\int_{\gamma} F \cdot d\vec{r}$.

If S is the unit disc in the xy-plane, oriented with unit normal vector pointing upward, then $\gamma = \partial S$, and by Stokes' Theorem we have

$$\int_{\gamma} F \cdot d\vec{r} = \iint_{S} (\nabla \times F) \cdot d\vec{S} = \iint_{S} \langle 0, 0, 2y + 1 \rangle \cdot d\vec{S}.$$

We can parametrize S by

 $\vec{r}(u,v) = \langle u,v,0\rangle \qquad u^2 + v^2 \le 1 \qquad \vec{r}_u \times \vec{r}_v = \langle 1,0,0\rangle \times \langle 0,1,0\rangle = \langle 0,0,1\rangle.$

This is the correct orientation. (If it were not, we could interchange u and v in the parametrization, or just multiply our answer by -1.) Then

$$d\vec{S} = \vec{r_u} \times \vec{r_v} \, du \, dv = \langle 0, 0, 1 \rangle \, du \, dv$$
$$\iint_S (\nabla \times F) \cdot d\vec{S} = \iint_{u^2 + v^2 \le 1} \langle 0, 0, 2v + 1 \rangle \cdot \langle 0, 0, 1 \rangle \, du \, dv = \iint_{u^2 + v^2 \le 1} 2v + 1 \, du \, dv.$$

By symmetry we have

$$\iint_{u^2+v^2\leq 1} 2v\,du\,dv = 0.$$

$$\iint_{u^2+v^2\leq 1} 1\,du\,dv = (\text{area of region } u^2+v^2\leq 1) = \pi.$$

Therefore

$$\int_{\gamma} F \cdot d\vec{r} = \iint_{S} (\nabla \times F) \cdot d\vec{S} = \iint_{u^{2} + v^{2} \le 1} 2v + 1 \, du \, dv = \pi.$$

We could also do this without parametrizing S: Since S is in the xy plane, oriented with upward pointing normal, we have $\vec{n} = \langle 0, 0, 1 \rangle$, and

$$\begin{split} \iint_{S} (\nabla \times F) \cdot d\vec{S} &= \iint_{S} \langle 0, 0, 2y+1 \rangle \cdot \vec{n} \, dS = \iint_{S} \langle 0, 0, 2y+1 \rangle \cdot \langle 0, 0, 1 \rangle \, dS = \\ \iint_{S} 2y+1 \, dS &= \underbrace{\iint_{S} 2y \, dS}_{0 \text{ by symmetry}} + \iint_{S} 1 \, dS = 0 + \operatorname{area}(S) = \pi. \end{split}$$

Example: Suppose that F is a vector field on \mathbb{R}^3 whose components have continuous partial derivatives everywhere, and when z = 0 we have

$$(\nabla \times F)(x, y, 0) = \langle 0, 0, 3 \rangle$$

Let S be the top half of the unit sphere, oriented with \vec{n} pointing up. Find

$$\iint_{S} (\nabla \times F) \cdot d\vec{S}.$$

The boundary of S is γ , the unit circle in the xy-plane oriented counterclockwise as viewed from above. By Stokes' Theorem, we have

$$\iint_{S} (\nabla \times F) \cdot d\vec{S} = \int_{\gamma} F \cdot d\vec{r}.$$

Let D be the unit disc in the xy-plane, oriented with \vec{n} pointing up. Then γ is also the boundary of D, and by Stokes' Theorem, we have

$$\int_{\gamma} F \cdot d\vec{r} = \iint_{D} (\nabla \times F) \cdot d\vec{S}.$$

On D, we have $\nabla \times F = \langle 0, 0, 3 \rangle$ and $\vec{n} = \langle 0, 0, 1 \rangle$, so

Putting this all together,

$$\iint_{S} (\nabla \times F) \cdot d\vec{S} = \int_{\gamma} F \cdot d\vec{r} = \iint_{D} (\nabla \times F) \cdot d\vec{S} = 3\pi.$$

Example: Evaluate $\int_{\gamma} F \cdot d\vec{r}$ where $F(x, y, z) = \langle yz, xz, xy \rangle$ and γ is the portion of the circle $x^2 + z^2 = 1$, y = 1 above the xy plane, oriented from (1, 1, 0) to (-1, 1, 0).

In the plane y = 1:



Using Stokes' Theorem: Let ψ be the line segment from (-1, 1, 0) to (1, 1, 0).

Then $\gamma + \psi$ is the boundary of D, the half-disc $x^2 + z^2 \leq 1$, $z \geq 0$, y = 1, oriented appropriately. (In the picture, \vec{n} should be pointing at us, which gives $\vec{n} = \langle 0, -1, 0 \rangle$.) By Stokes's Theorem

$$\int_{\gamma} F \cdot d\vec{r} + \int_{\psi} F \cdot d\vec{r} = \iint_{D} (\nabla \times F) \cdot d\vec{S}.$$

We can compute $\nabla \times F = \langle 0, 0, 0 \rangle$, so

$$\iint_D (\nabla \times F) \cdot d\vec{S} = \iint_D \langle 0, 0, 0 \rangle \cdot d\vec{S} = 0.$$

On ψ , we have z = 0, so $F = \langle 0, 0, xy \rangle$. Also, on ψ we have $d\vec{r} = \vec{T} ds$ and $\vec{T} = \langle 1, 0, 0 \rangle$, so

$$\int_{\psi} F \cdot d\vec{r} = \int_{\psi} F \cdot \vec{T} \, ds = \int_{\psi} \langle 0, 0, xy \rangle \cdot \langle 1, 0, 0 \rangle \, ds = 0.$$

Therefore, we have

$$\int_{\gamma} F \cdot d\vec{r} + 0 = 0;$$
$$\int_{\gamma} F \cdot d\vec{r} = 0.$$

Example continued with some other methods:

Evaluate $\int_{\gamma} F \cdot d\vec{r}$ where $F(x, y, z) = \langle yz, xz, xy \rangle$ and γ is the portion of the circle $x^2 + z^2 = 1, y = 1$ above the xy plane, oriented from (1, 1, 0) to (-1, 1, 0).

Using the Fundamental Theorem of Line Integrals: The fact that $\nabla \times F = \langle 0, 0, 0 \rangle$ on all of \mathbb{R}^3 tells us that F is conservative. If we look for a potential function for F we will discover that $F = \nabla f$ where f(x, y, z) = xyz. Therefore

$$\int_{\gamma} F \cdot d\vec{r} = \int_{\gamma} \nabla f \cdot d\vec{r} = f(-1, 1, 0) - f(1, 1, 0) = 0$$

Directly: Parametrize γ by $\vec{r}(t) = \langle \cos t, 1, \sin t \rangle$ for $0 \le t \le \pi$. Then

$$\int_{\gamma} \langle yz, xz, xy \rangle \cdot d\vec{r} = \int_{0}^{\pi} \langle \sin t, \cos t \sin t, \cos t \rangle \cdot \langle -\sin t, 0 \cos t \rangle \, dt = \int_{0}^{\pi} (\cos^{2} t - \sin^{2} t) \, dt = \int_{0}^{\pi} \left(\frac{1 + \cos(2t)}{2} - \frac{1 - \cos(2t)}{2} \right) \, dt = \int_{0}^{\pi} \cos(2t) \, dt = \frac{\sin(2t)}{2} \Big|_{t=0}^{t=\pi} = 0.$$

Example: S is the surface parametrized by $\vec{r}(u,v) = \langle u \cos v, u \sin v, v \rangle$, $0 \le u \le 1$, $0 \le v \le \frac{\pi}{2}$, oriented so \vec{n} points in the direction of $\vec{r}_u \times \vec{r}_v$, and γ is the positively oriented boundary of S.



Determine which way the unit vector \vec{n} points, and draw arrows on the picture to indicate the orientation of γ .

If $F(x, y, z) = \langle z, x^2, y \rangle$, find

$$\int_{\gamma} F \cdot d\bar{r}$$

in two ways, by directly computing the line integral, and by using Stokes' Theorem.

Example: Use Stokes's Theorem to find $\iint_{S} (\nabla \times F) d\vec{S}$ where S is the portion of the cone $z = 1 - \sqrt{x^2 + y^2}$ in the first octant, oriented so \vec{n} points away from the z-axis, and $F(x, y, z) = \langle -y + (x + z) \cos x, x - zy^3, e^{xy} \rangle$.

Example: Suppose that F is a vector field whose components have continuous partial derivatives, and S is a sphere with outward-pointing normal. Use Stokes' Theorem to show that

$$\iint_{S} (\nabla \times F) \cdot d\vec{S} = 0.$$

Challenge: Suppose that F is a fluid flow field that varies over time, so that F(x, y, z, t) is the velocity of fluid flow at point (x, y, z) and time t. If S is an oriented surface, how would you use integrals to find how much fluid flows through S between times t = a and t = b?