

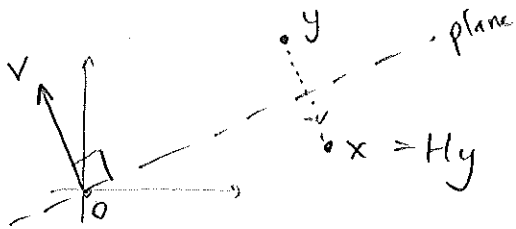
M116 WORKSHEET : Householder Reflectors

4/8/14.
Summitt

We want unitary Q_1 turning $a_1 \in \mathbb{R}^m$ into $\begin{bmatrix} \alpha \\ 0 \\ \vdots \\ 0 \end{bmatrix} = Q_1 a_1$ (*)

a) How big is α ?

Now find the matrix H which reflects $y \in \mathbb{R}^m$ through the plane through the origin with normal $v \in \mathbb{R}^m$:



Hints: use picture., try $\|v\|=1$ case first.

b) You should get $H = I + (\text{rank-1})$ What minimum effort is needed to apply this to a general vector y , i.e. the matrix $x = Hy$?

We pick Q_1 of the form H :

c) Explain why if (*) holds then v must be of the form $\gamma \left(a_1 + \begin{bmatrix} \beta \\ 0 \\ \vdots \\ 0 \end{bmatrix} \right)$ & we can choose $\gamma=1$.

d) Let $f = \begin{bmatrix} a_{21} \\ \vdots \\ a_{m1} \end{bmatrix}$, i.e. $a_1 = \begin{bmatrix} a_{11} \\ f \end{bmatrix}$ and so $v = \begin{bmatrix} a_{11} + \beta \\ f \end{bmatrix}$.

By considering (*) & your formula for H , solve for β & simplify:

BONUS: which of the two solutions has less relative error due to rounding error?

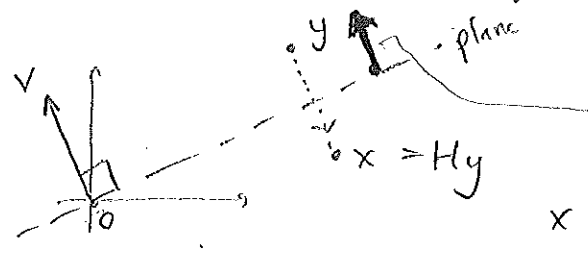
M116 WORKSHEET : Householder Reflectors

--- NO SOLUTIONS ---

We want unitary Q_1 turning $a_1 \in \mathbb{R}^m$ into $\begin{bmatrix} \alpha \\ 0 \\ \vdots \\ 0 \end{bmatrix} = Q_1 a_1$ (*)

a) How big is α ? $\alpha = \|a_1\|$ since $\|Q_1 a_1\| = \|a_1\|$ by unitarity.

Now find the matrix H which reflects $y \in \mathbb{R}^m$ through the plane through the origin with normal $v \in \mathbb{R}^m$:



Hints: use picture, try $\|v\|=1$ case first. This vector = $(v^T y)v$ in the case $\|v\|=1$.

$$x = y - 2(\text{this vector}) = y - 2v(v^T y)$$

Matrix doing this for general y is $H = I - 2vv^T$ (check it)

If $\|v\| \neq 1$ then $H = I - 2 \frac{vv^T}{v^T v}$ indeed: (scalar) vv^T

b) You should get $H = I - 2 \frac{vv^T}{v^T v}$ (rank-1) What minimum effort is needed to apply this to a general vector y , i.e. the matrix $x = Hy$?

We pick Q_1 of the form H : $H y = y - \underbrace{2 \frac{v^T y}{v^T v} v}_{O(m) \text{ subtractions}} = O(m) \text{ effort.}$

c) Explain why if (*) holds then v must be of the form $\gamma \begin{pmatrix} a_1 \\ \beta \\ 0 \\ \vdots \\ 0 \end{pmatrix}$ & we can choose $\gamma = 1$. Since $H a_1$ must be $\begin{pmatrix} \alpha \\ 0 \\ \vdots \\ 0 \end{pmatrix}$ then $\begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_m \end{bmatrix}$ must be $\propto \begin{pmatrix} a_{11} \\ \beta \\ 0 \\ \vdots \\ 0 \end{pmatrix}$

d) Let $f = \begin{bmatrix} a_{21} \\ \vdots \\ a_{m1} \end{bmatrix}$, i.e. $a_1 = \begin{bmatrix} a_{11} \\ f \end{bmatrix}$ and so $v = \begin{bmatrix} a_{11} + \beta \\ f \end{bmatrix}$.

By considering (*) & your formula for H , solve for β & simplify: $\begin{bmatrix} \alpha \\ 0 \end{bmatrix} = H a_1 = a_1 - 2 \frac{v a_1^T}{v^T v} v = \begin{bmatrix} a_{11} \\ f \end{bmatrix} - 2 \frac{v a_1^T}{v^T v} \begin{bmatrix} a_{11} + \beta \\ f \end{bmatrix}$ since f 's cancel, we must have $2 \frac{v a_1^T}{v^T v} = 1$.

So, $v^T v = 2 v a_1^T$, i.e. $a_{11}^2 + 2\beta a_{11} + \beta^2 + \|f\|^2 = 2(a_{11}^2 + \beta a_{11} + \|f\|^2)$ i.e. $\beta^2 = a_{11}^2 + \|f\|^2 = \|a_1\|^2$, $\beta = \pm \|a_1\|$.

ONUS: which of the two solutions has less relative error due to rounding error? $\text{sgn}(a_{11})$.